



DWIN Linux Screen Development Guide

(40 Series & 40ZOS-1 Series)

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1 Product Introduction

1.1 Product Feature

DWIN Linux screen 40 series:

CPU: RK3566, Quad-core ARM Cortex-A55, 1.8GHz

RAM: 2GB LPDDR4

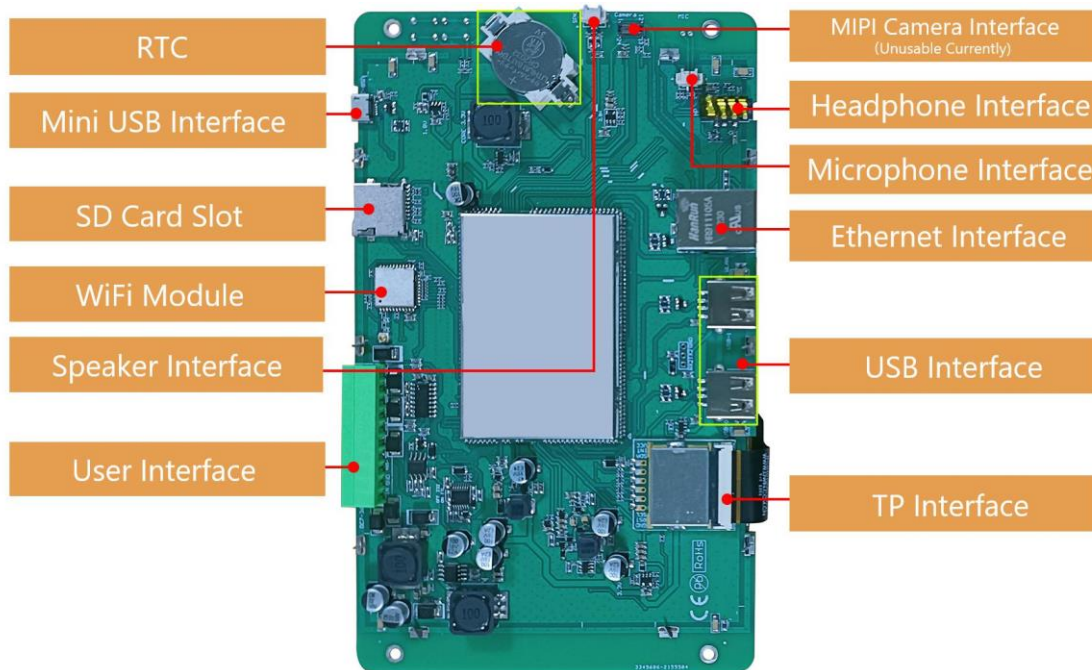
Flash: 8GB EMMC5.0

Linux Version: Linux 4.19

Debian version (module suffix is ZOS-1)



(DMG12800T070_40WTC front)



(DMG12800T070_40WTC back)

1.1.1 Development Method

QT and LVGL options.

1.1.2 Documentation

Documents: <https://www.dwin-global.com/development-guide/>

Tool: <https://www.dwin-global.com/tool-page/>

Tutorial on YouTube:

<https://youtube.com/playlist?list=PLKfWyFPPaoDr3Vq98orVxJqKA5MDaliN&si=BVVDmdfCopcH--nK>

1.1.3 Shipping List (for reference)

- screen ×1 piece
- antenna × 1 piece

1.1.4 Optional Accessories

- **Speaker**

DWIN material code B01851, cable length 180 mm, with socket 2PIN_1.25, $88 \pm 3\text{dB}$, 8Ω , 0.8W

- **SD card**

- **4G module**

China and India: LUAT Air780EI

Europe: QUECTEL EC200A-EU

Australia: QUECTEL EC200A-AU

- **Camera**

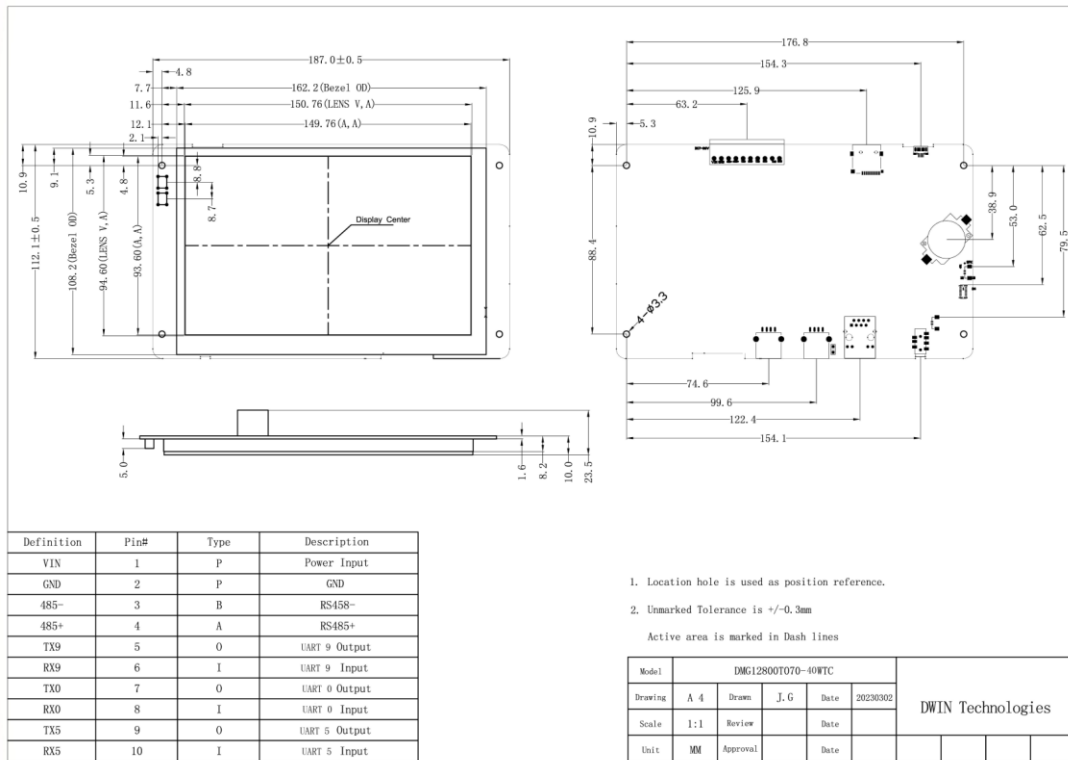
Support camera with USB interface

1.2 Wiring

Regarding the definition of serial please refer to the related datasheet as below,

Peripherals and Interfaces

| Properties | Parameters | Description |
|------------|----------------|---------------|
| COM | 2-way RS232 | UART5 & UART9 |
| | 1-way RS485 | UART8 |
| | 1-way TTL/COMS | UART0 |

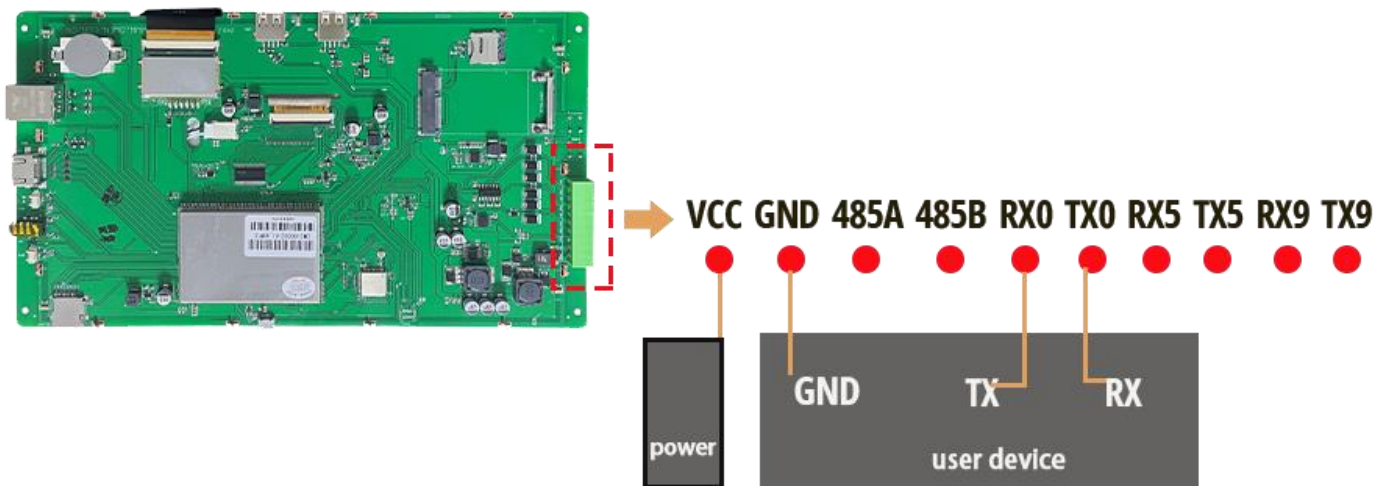


1.2.1 Hardware Connection

GND, Ground, connect to GND pin of the user device.

TXD, Transmit, connect to TX pin of the user device.

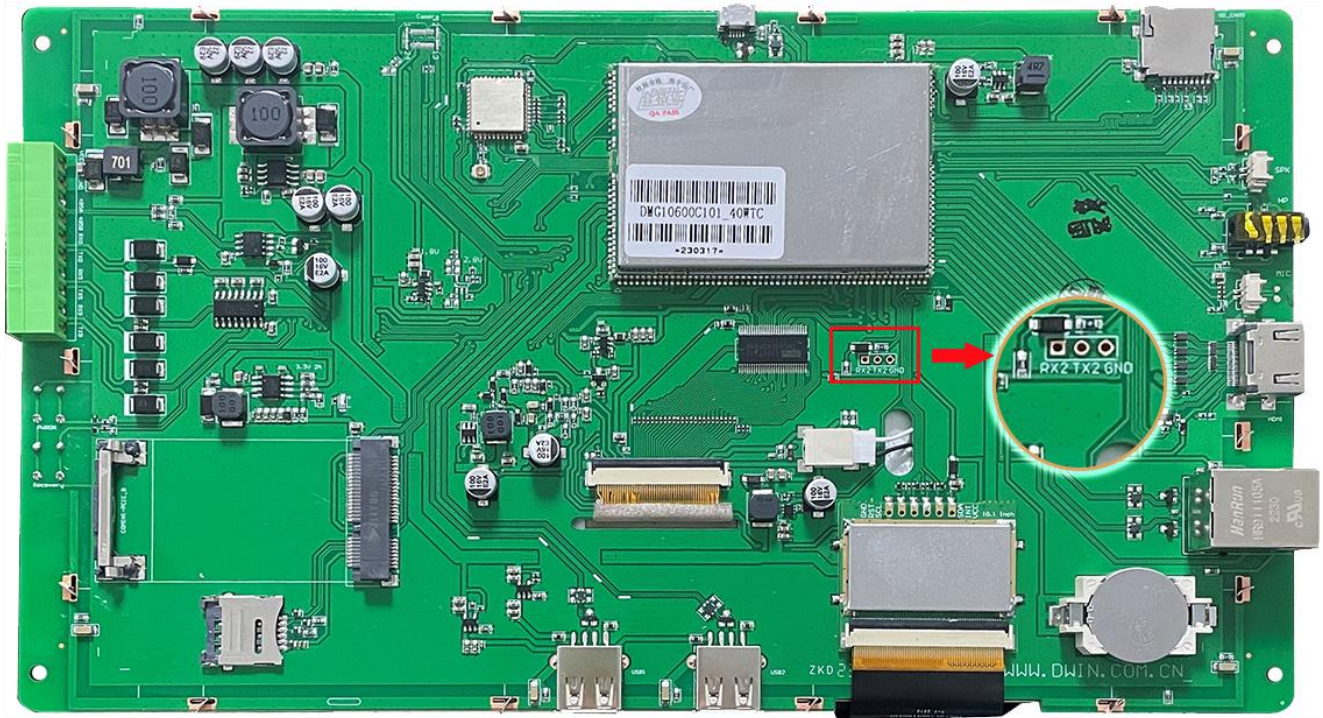
RXD, Receive, connect to RX pin of the user device.



1.2.2 Serial Parameter Setting

Regarding baud rate, UART 2 is 1500000, else are 115200.

For programming purposes, serial ports are identified by names that follow the pattern ttyS, such as ttyS0 or ttyS1.



1.2.3 Other Tools

DC regulated 12V power supply is recommended for testing, using SD card with 1~16 GB memory for project downloading.

2 Environment Setup

2.1 Ubuntu16.04 Configuration

2.1.1 Introduction

This chapter will introduce the installation of a virtual machine and the configuration of Ubuntu16.04. If you have already installed Ubuntu16.04, you can [click here](#).

2.1.2 Environment Requirements

CPU: no specific requirement Memory: generally over 2G.

Host machine OS: Windows XP, Windows 7 and above.

Software version: you can choose VMware workstation 10 and above for Windows according to your needs, it is not recommended to use previous versions.

Note:

This example will use VMware Workstation 15 Pro for installation demonstration.

2.1.3 VMware Workstation Installation

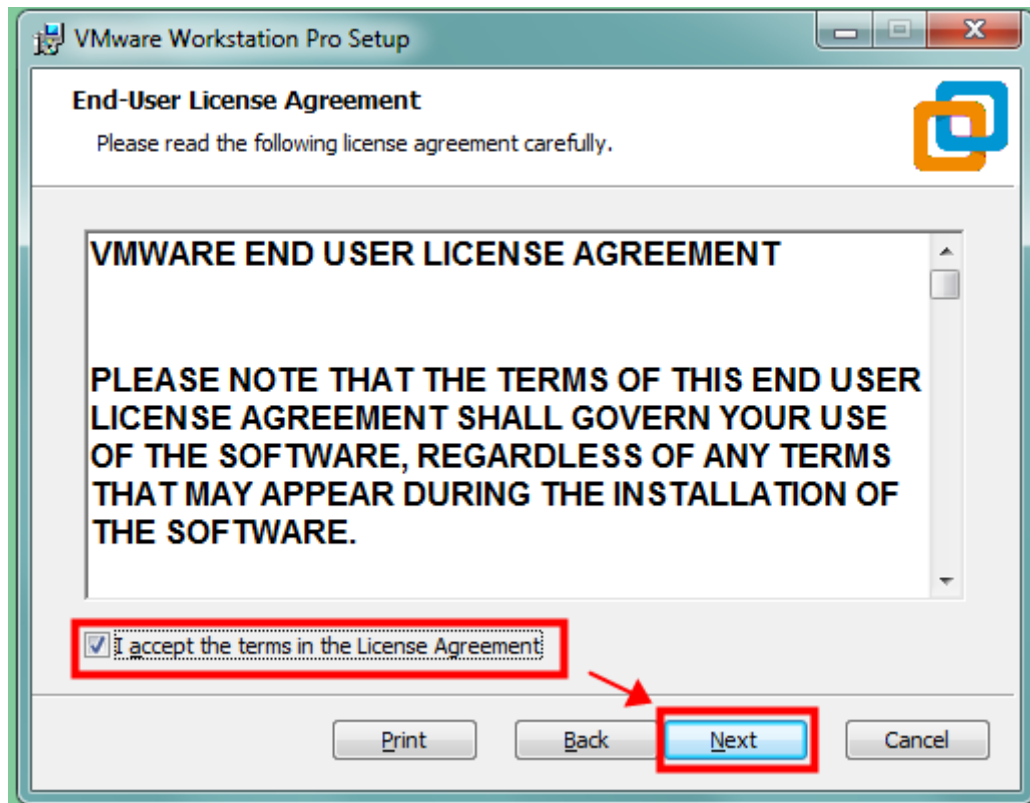
(1) Download VMware Workstation pro installation package on the official website below.

<https://www.vmware.com/products/workstation-pro.html>

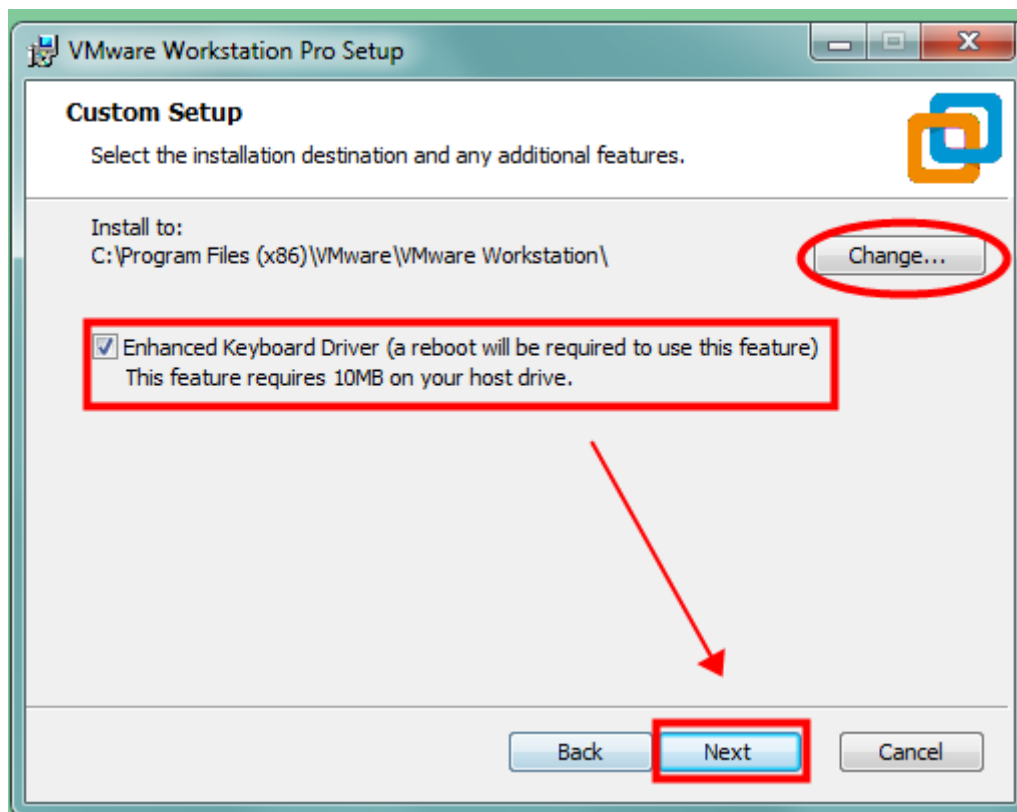


(2) Double clicks on downloaded exe file to start the installation and click “Next”.

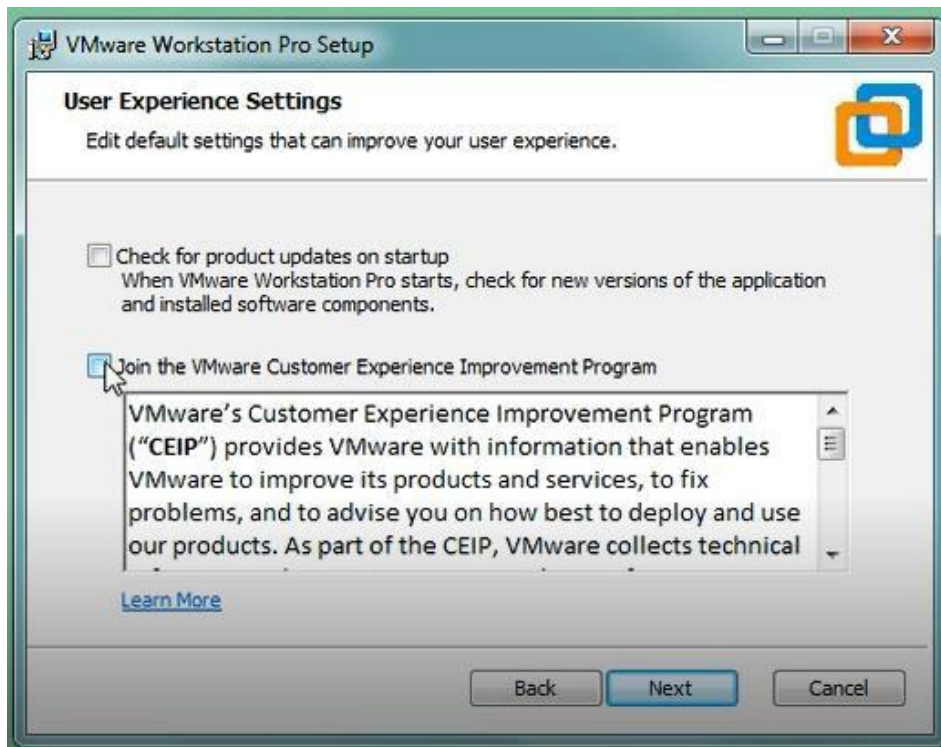
(3) Select “I accept the terms in the License Agreement” and click “Next”.



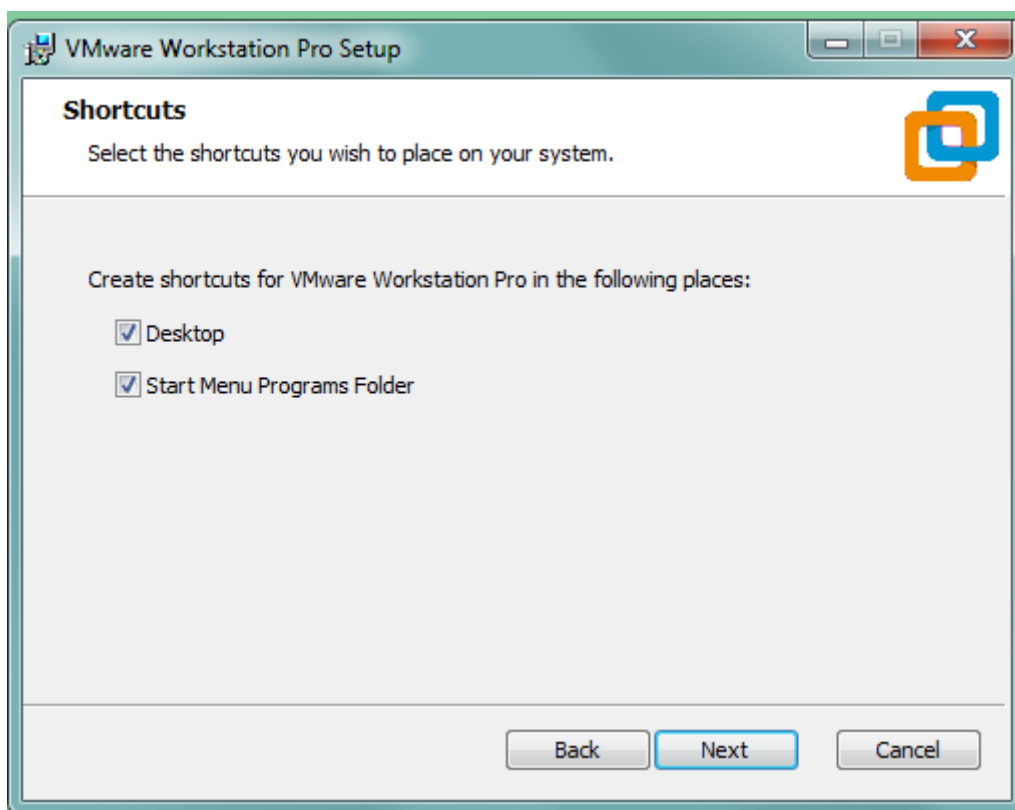
(4) Select the installation destination. Click “**Change**” if you want to install on another destination. Select “**Enhanced Keyboard...**” and then click “**Next**”.



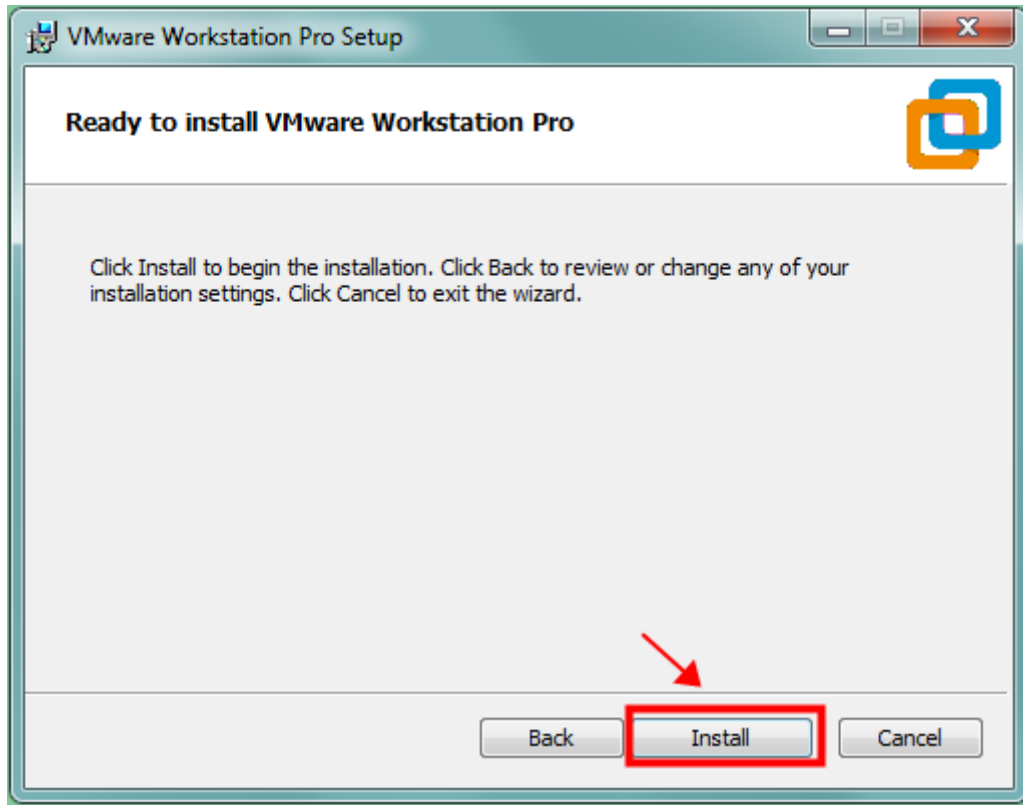
(5) Select “Check for product updates on startup” and “Join the VMware Customer Experience Improvement Program” based on what you need. Then click “Next”.



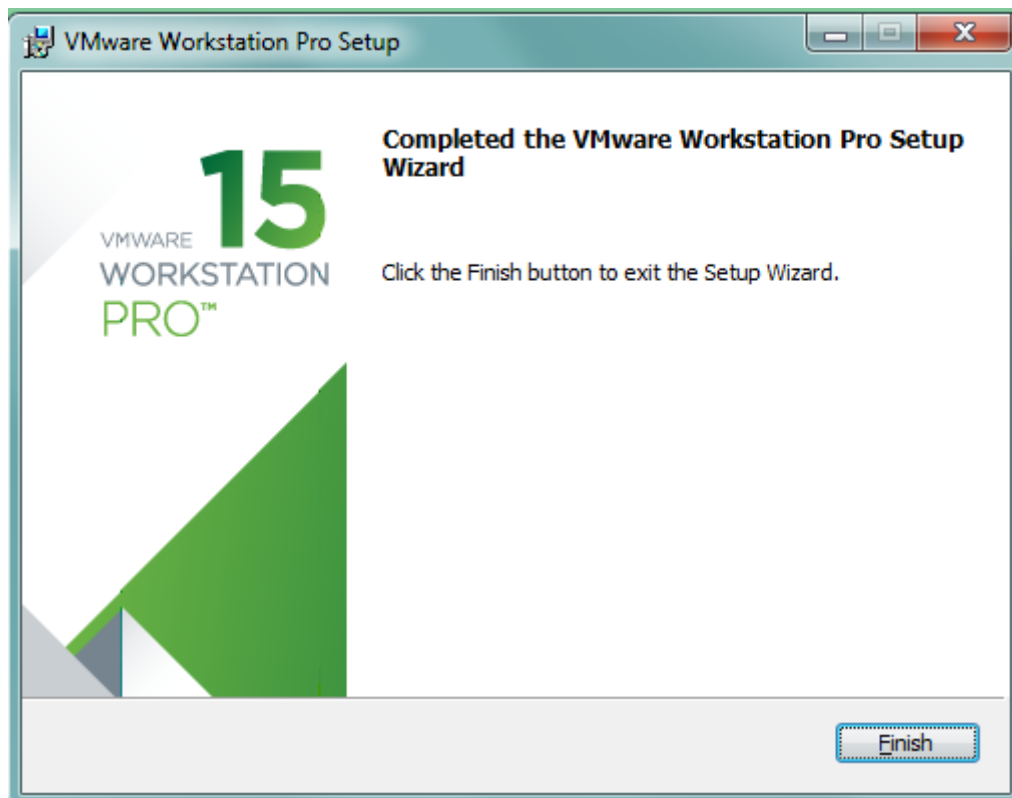
(6) Select the shortcuts you wish to place on your system. It's recommended to select both. Click **“Next”**.



(7) Click **“Install”** to start the installation.



(8) The installation is completed. Click “**Finish**” to exit the Setup Wizard.



2.1.4 Download Ubuntu

- (1) Download Ubuntu 16.04 from the official website below. <https://releases.ubuntu.com/16.04/>
- (2) Select “64-bit PC(AMD64) desktop image” to download “ubuntu-16.04.7-desktop-amd64.iso”.

Select an image

Ubuntu is distributed on two types of images described below.

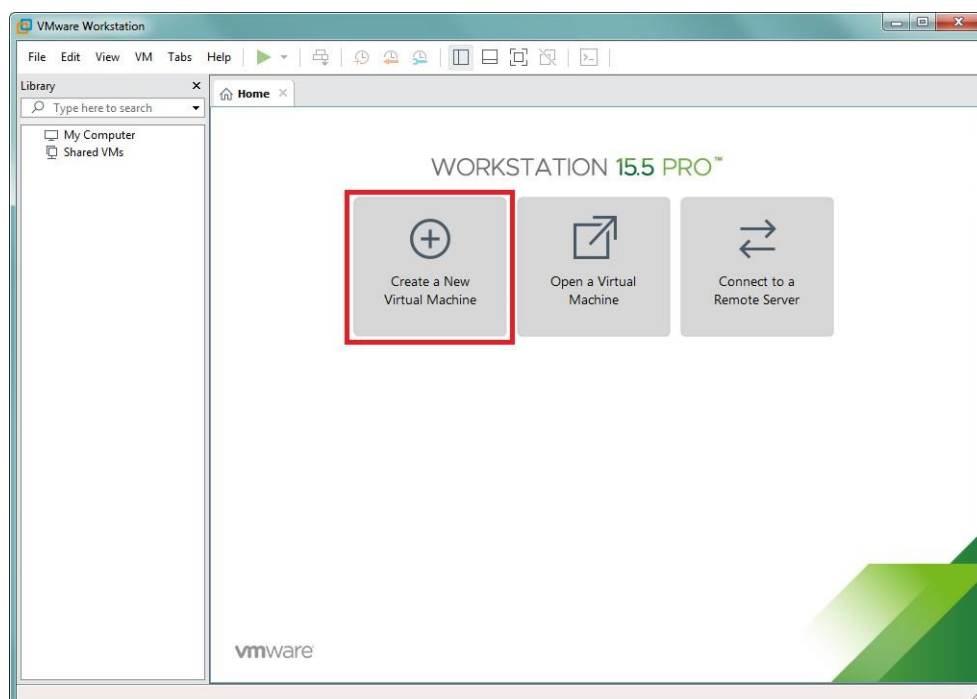
| | |
|---|--|
| <h3>Desktop image</h3> <p>The desktop image allows you to try Ubuntu without changing your computer at all, and at your option to install it permanently later. This type of image is what most people will want to use. You will need at least 384MiB of RAM to install from this image.</p> | <p>64-bit PC (AMD64) desktop image</p> <p>Choose this if you have a computer based on the AMD64 or EM64T architecture (e.g., Athlon64, Opteron, EM64T Xeon, Core 2). If you have a non-64-bit processor made by AMD, or if you need full support for 32-bit code, use the i386 images instead. Choose this if you are at all unsure.</p> <p>32-bit PC (i386) desktop image</p> <p>For almost all PCs. This includes most machines with Intel/AMD/etc type processors and almost all computers that run Microsoft Windows, as well as newer Apple Macintosh systems based on Intel processors.</p> |
| <h3>Server install image</h3> | <p>64-bit PC (AMD64) server install image</p> <p>Choose this if you have a computer based on the AMD64 or EM64T architecture (e.g., Athlon64, Opteron, EM64T Xeon, Core</p> |

2.1.5 Install Ubuntu

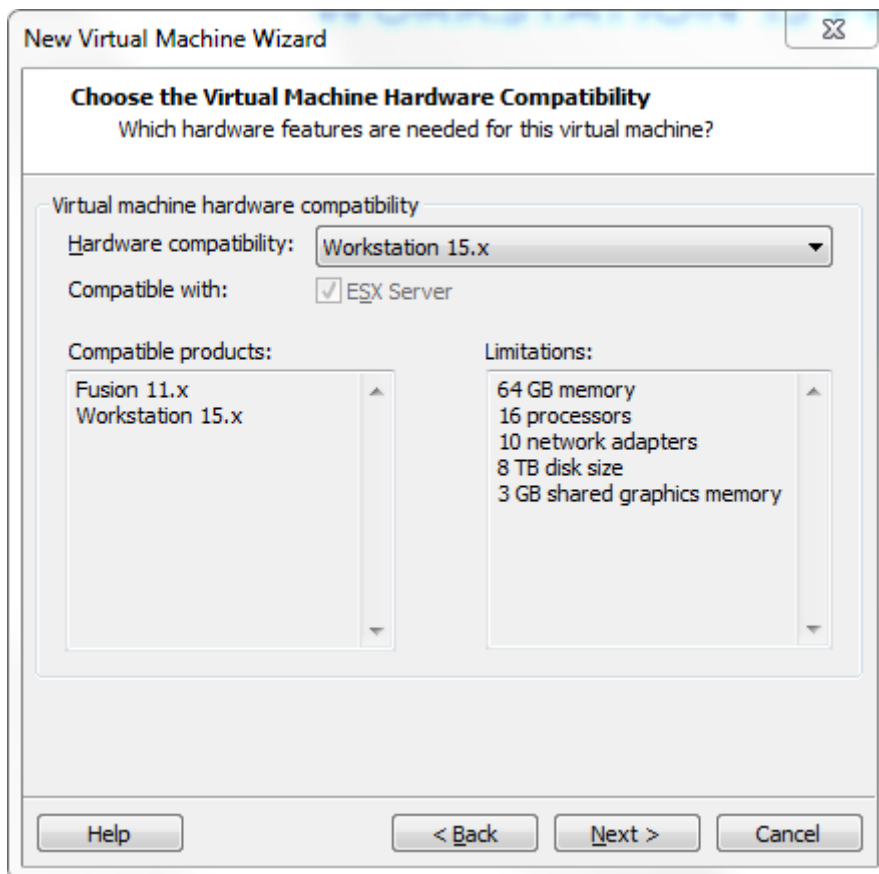
- (1) Open VMware Workstation Pro.



- (2) Click “Create a new virtual machine”.

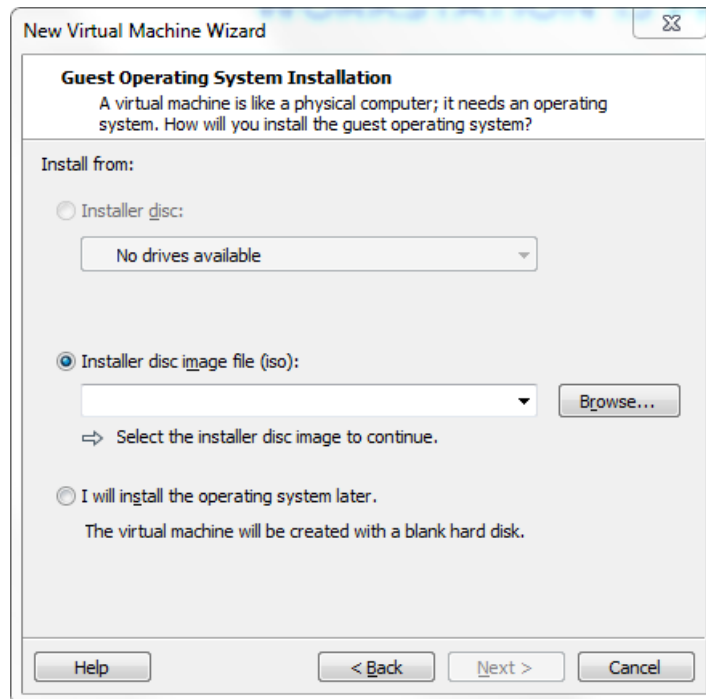


(3) Select “**Custom (advanced)**” and click “**Next**”.

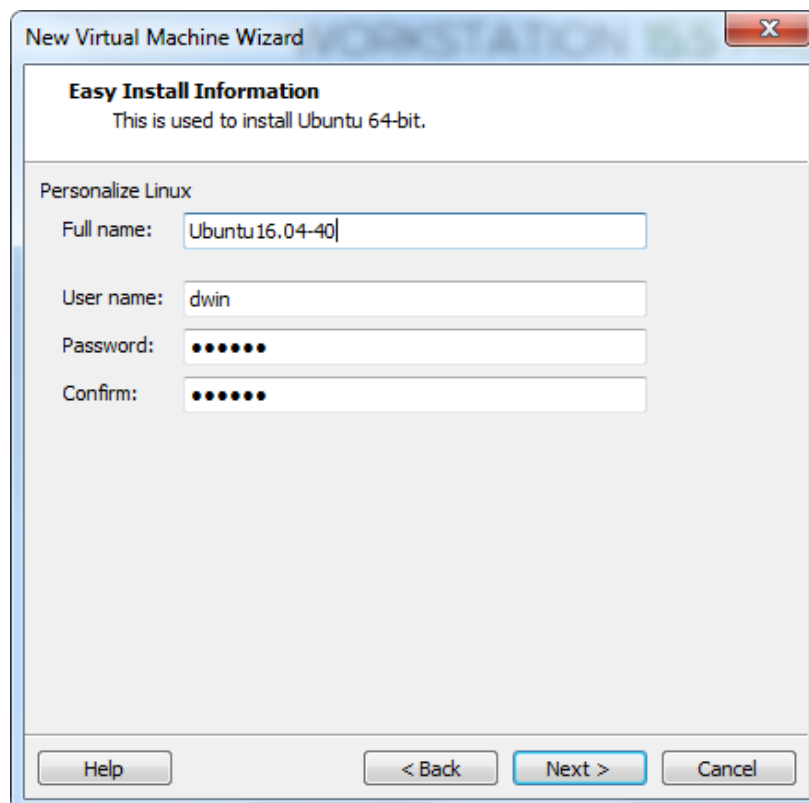


(5) Click “**Next**”

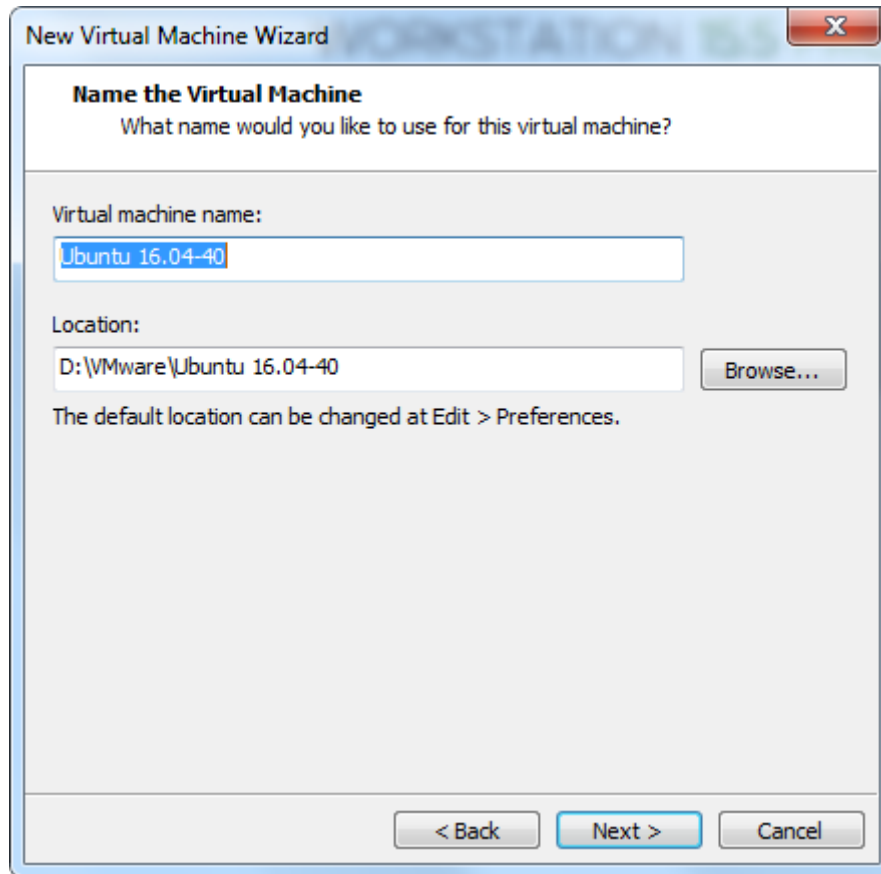
(6) Select “**Installer disc image file (iso)**”, next click “**Browse...**”, and select the downloaded Ubuntu *****.iso** file. This installer will automatically recognize and read file. Click “**Next**”.



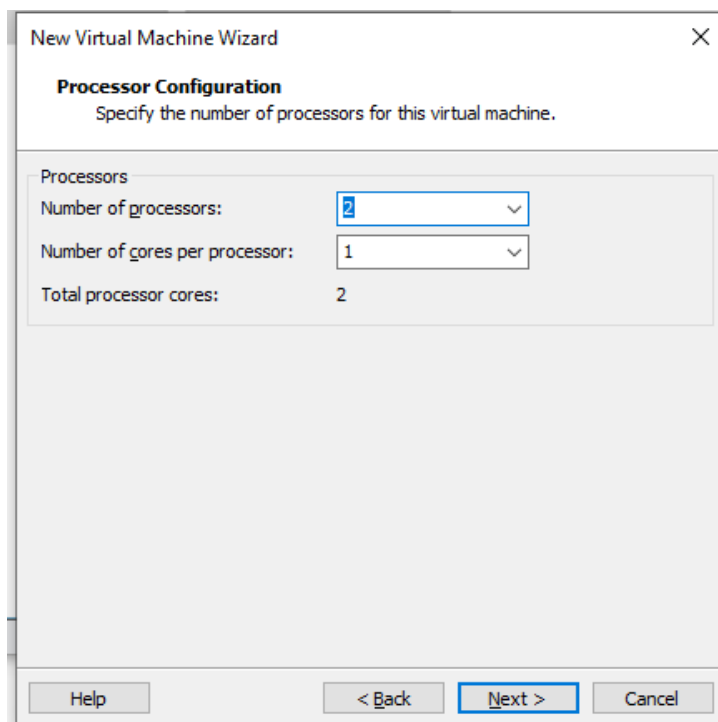
(7) Enter the custom name and password. The password is the Ubuntu login password and sudo privilege password. Click “**Next**”.



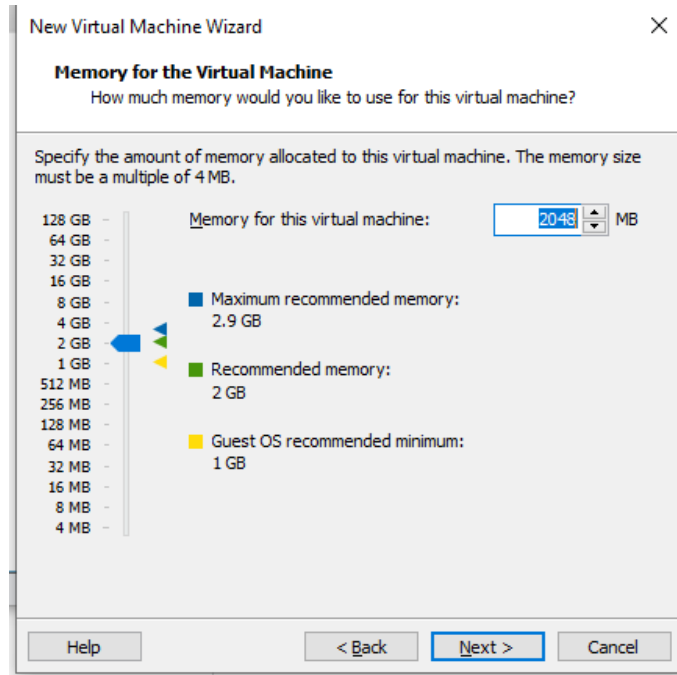
(8) Set the Ubuntu name and location, and click “**Next**”.



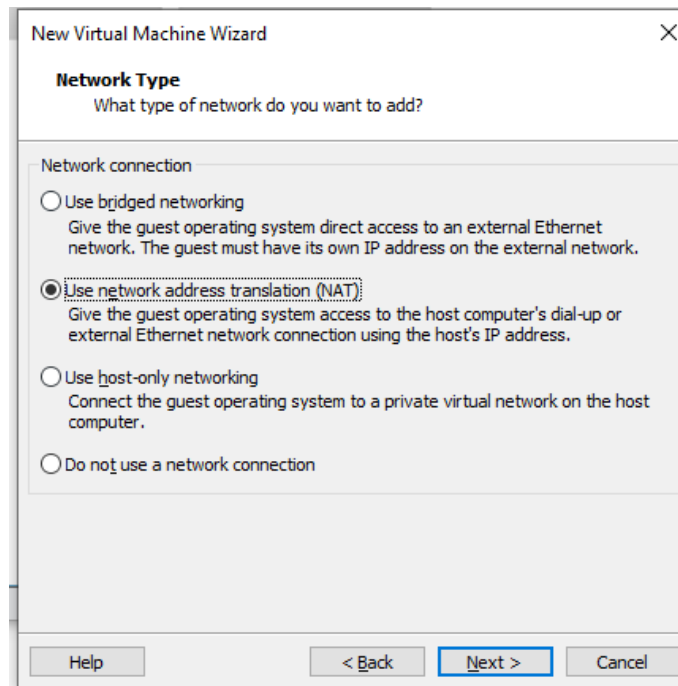
(8) According to needs and the computer configuration, allocate processors and cores (here the total number of processor cores is set to 2). Then click “**Next**”.



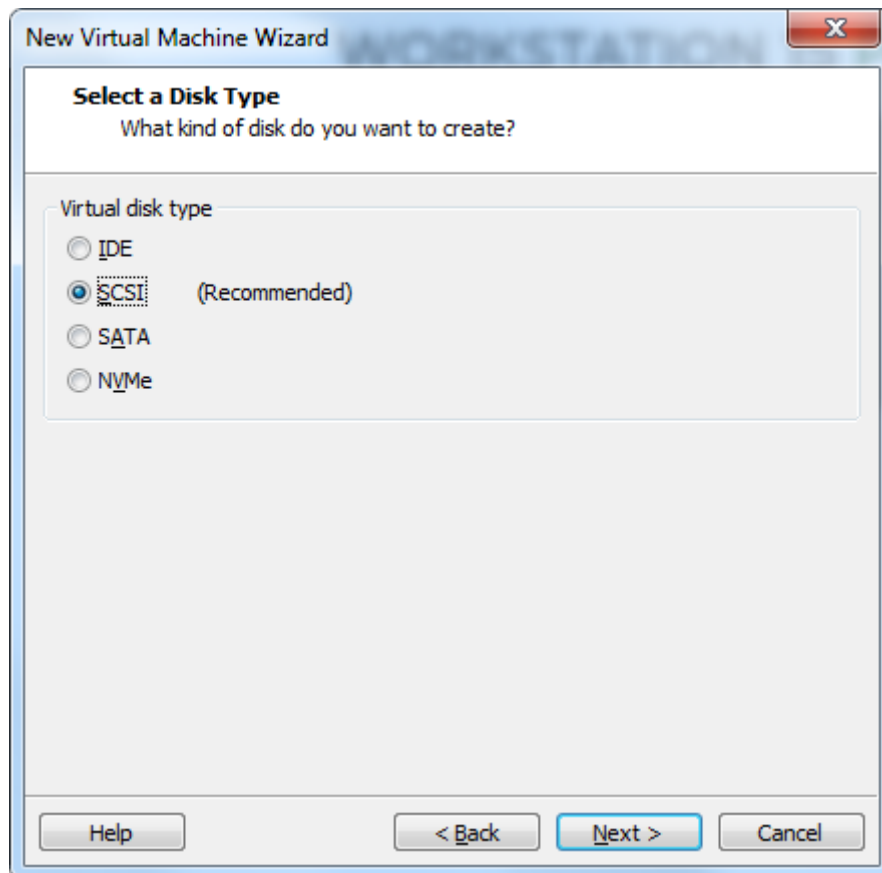
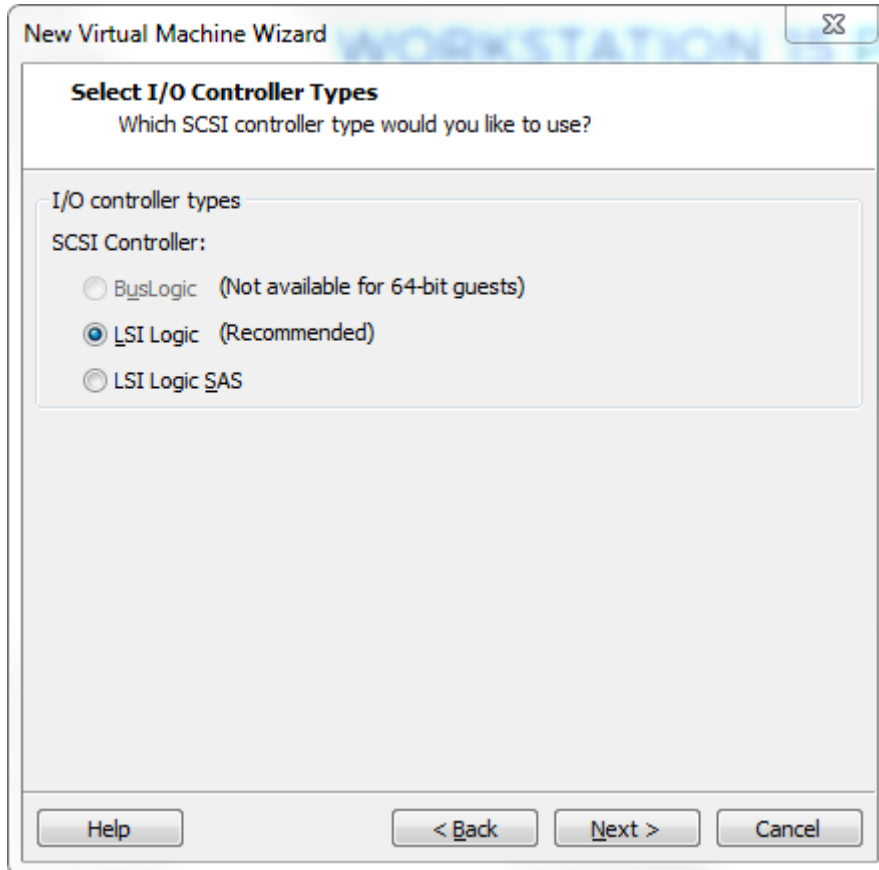
(9) The default operating memory is 2G (enough and changeable), click “**Next**”.



(10) Keep default configuration (or choose bridge network for tftp transfer). Click “Next”.

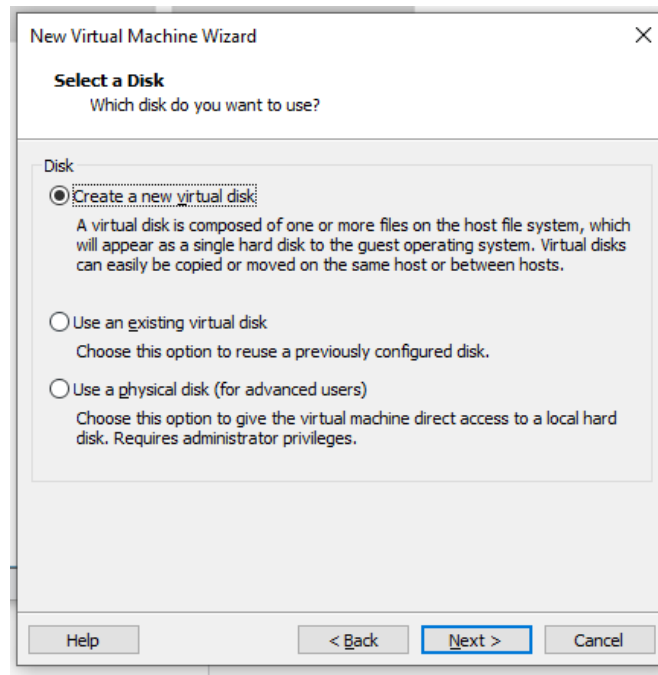


(11) Keep default and click “Next”.

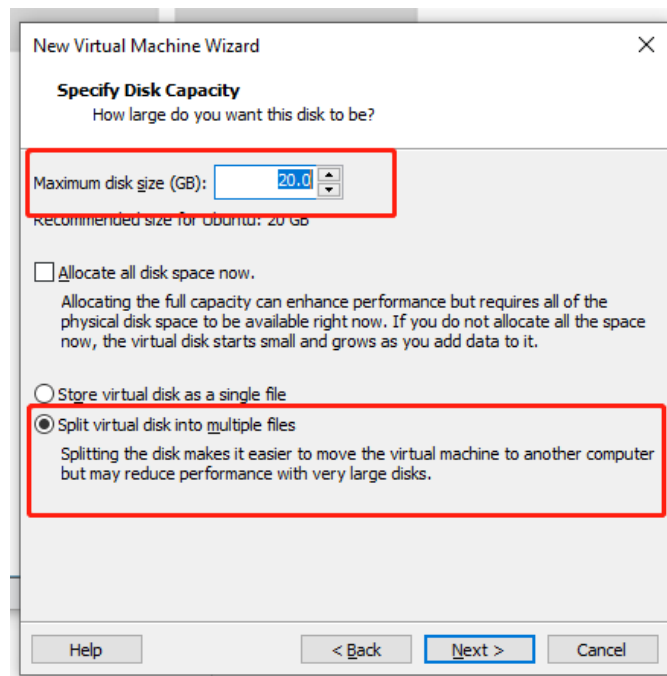


(12) Keep default and click “Next”.

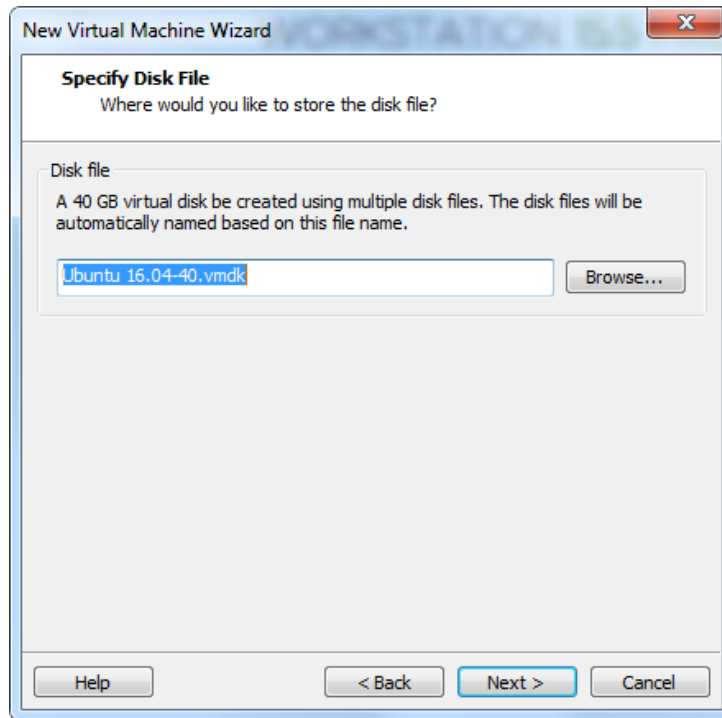
(13) Select “**Create a new virtual disk**” and click “**Next**”.



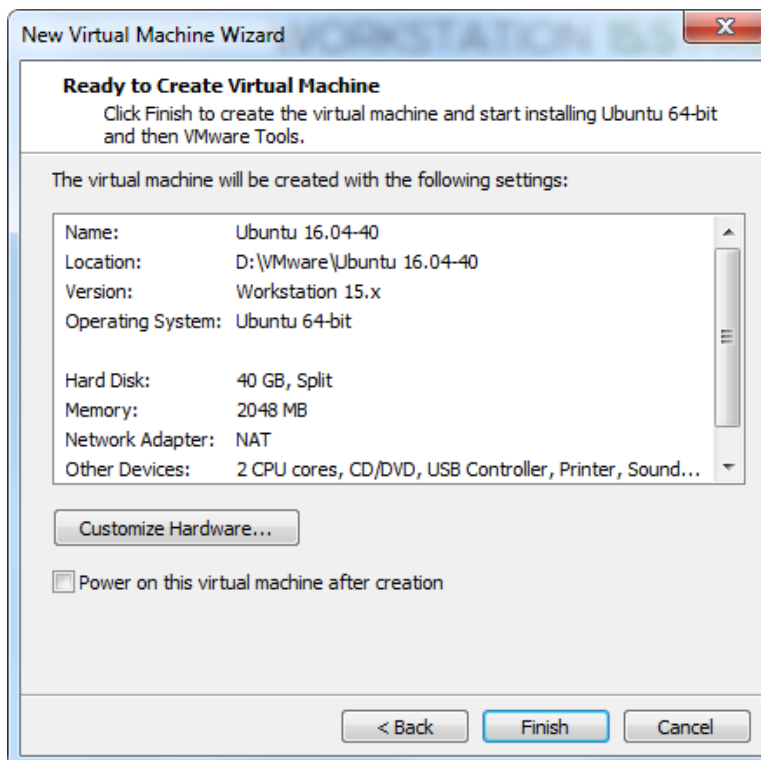
(14) Specify the disk capacity. If there is enough computer memory, it is recommended to set 30G or more because small memory may not be able to meet the subsequent demand. Select “**Split virtual disk into multiple files**”. Click “**Next**”. If the disk capacity is small, you can expand it (see subsequent sections).



(15) The disk will be named automatically. Keep the default and click “**Next**”.



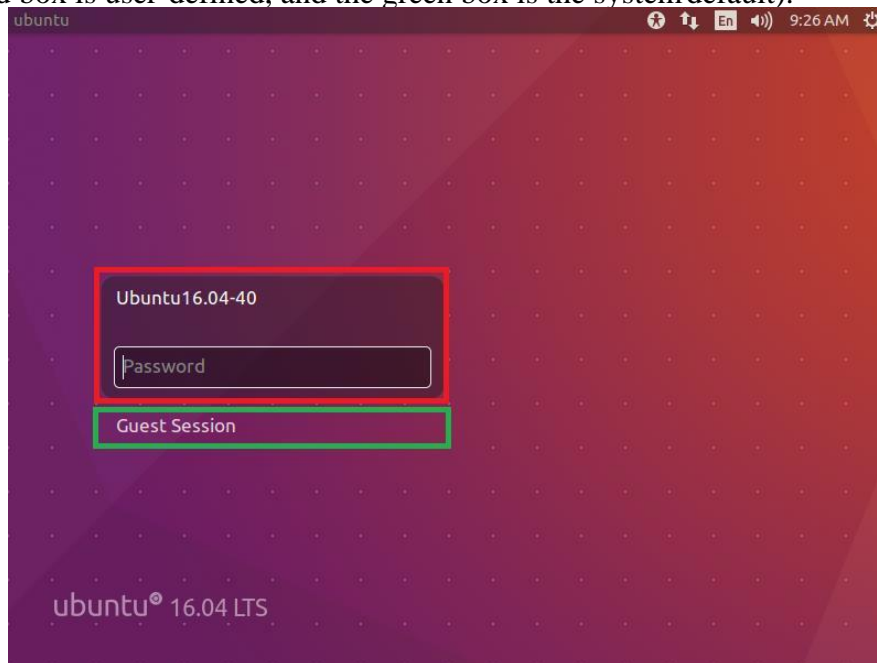
(16) Click “**Finish**” and the virtual machine will be opened and installed.



(17) Wait for a while.



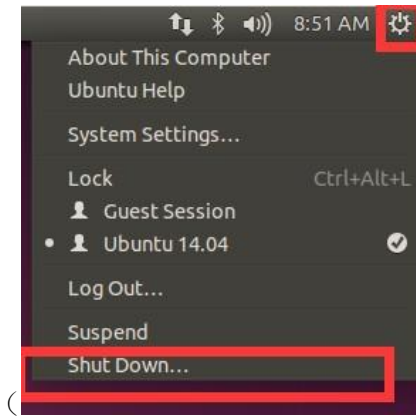
(18) When this page appears, the installation of Ubuntu is complete (Note: The login interface has two user login entries. The red box is user-defined, and the green box is the system default).



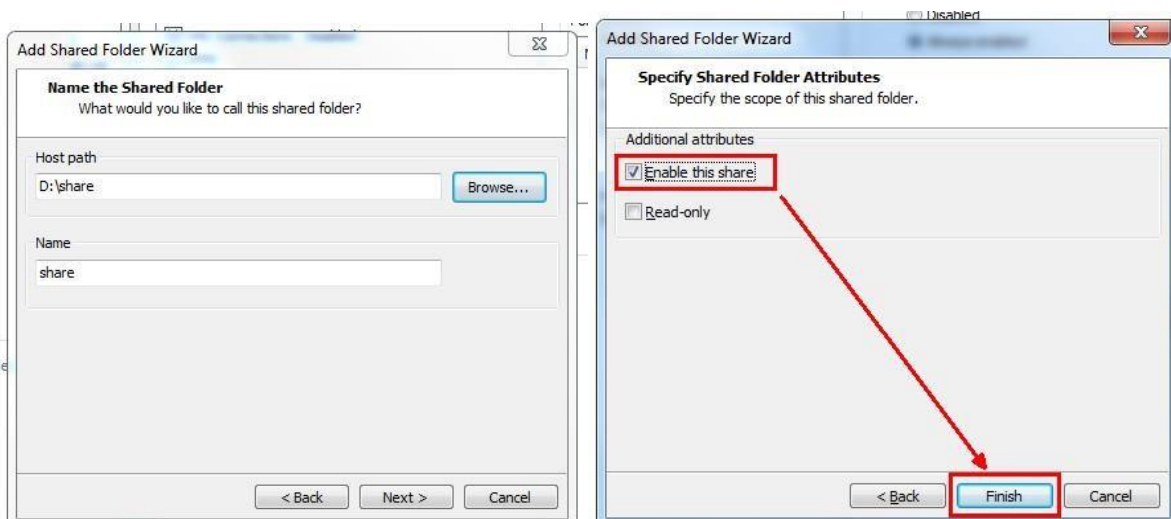
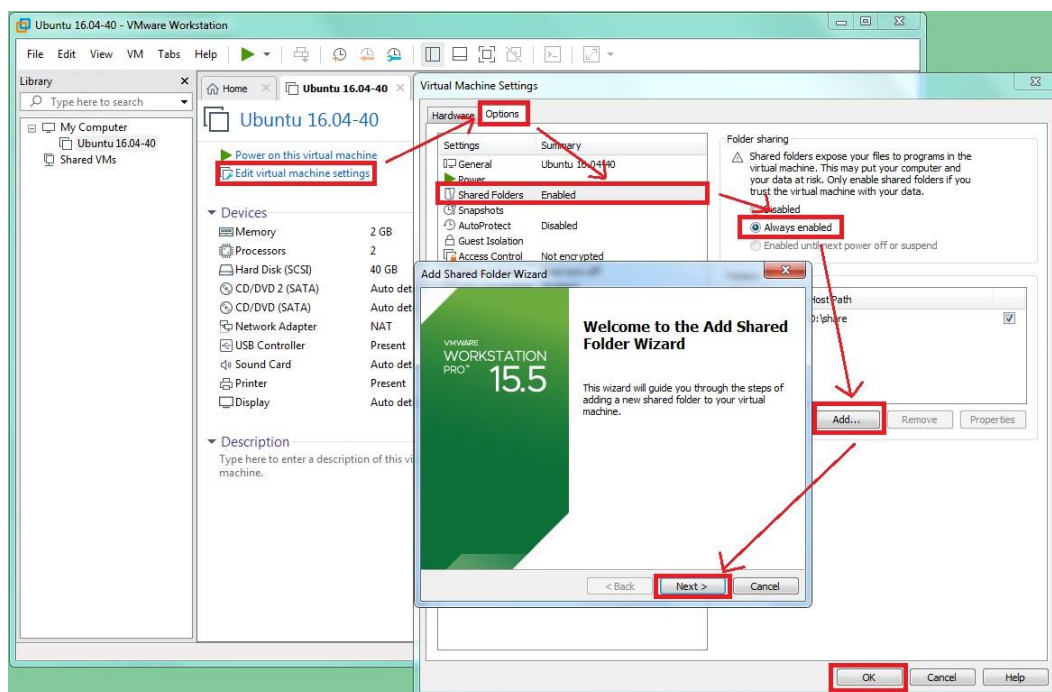
(19) Next, we'll start configuring some of the required settings for Ubuntu.

2.1.6 Shared Folder Setting

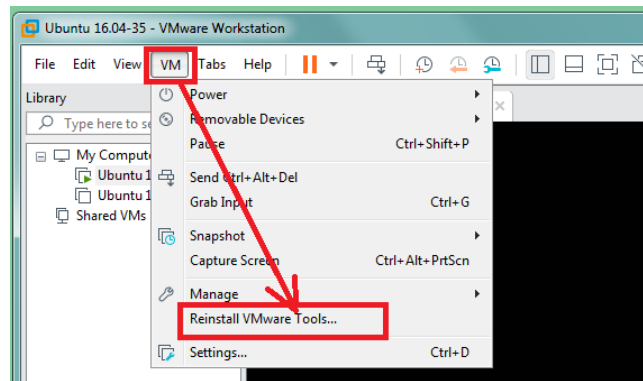
(1) Shut down Ubuntu.



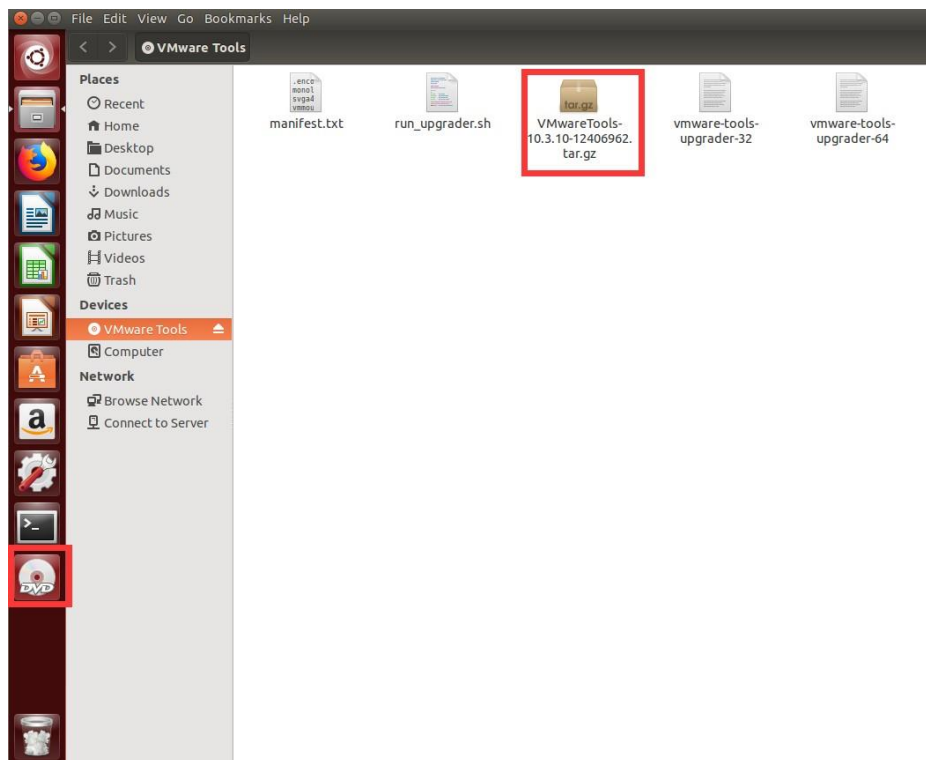
(2) After shutdown, click “Edit Virtual Machine Settings” -> “Options” -> “Shared Folder” -> “Always Enable” -> “Add”, to add a folder as a medium for file transfer between the host and the virtual machine. click “Next” and follow the Add Shared Folder Wizard. Finally click “OK”.



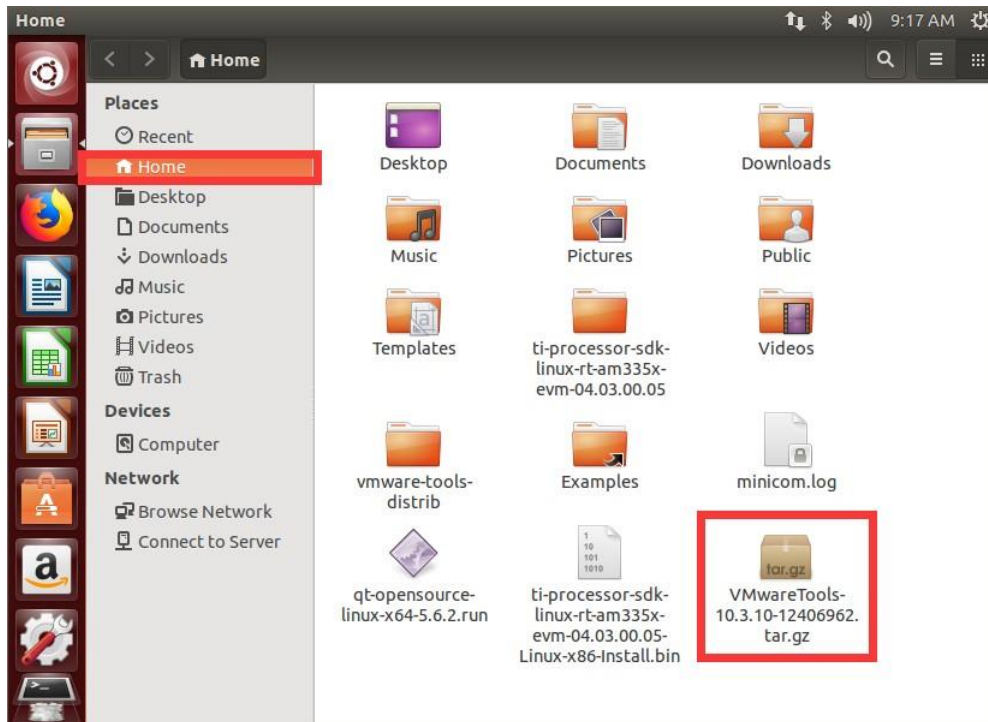
(3) Click “**Power on this virtual machine**” to start the virtual machine. Click “**VM**” -> “**Install VMware Tools**” (Note: The 'Install VMware Tools' is only selectable after powering on. In the example, VMware Tools have already been installed, so it shows 'Reinstall VMware Tools').



(4) Click the “**DVD**” icon and open it to see a tar file “**VMwareTools-10.3.10-12406962.tar.gz**”.



(5) Right click the tar file and click “**copy to**” a path with permission, e.g., to “**Home**”.



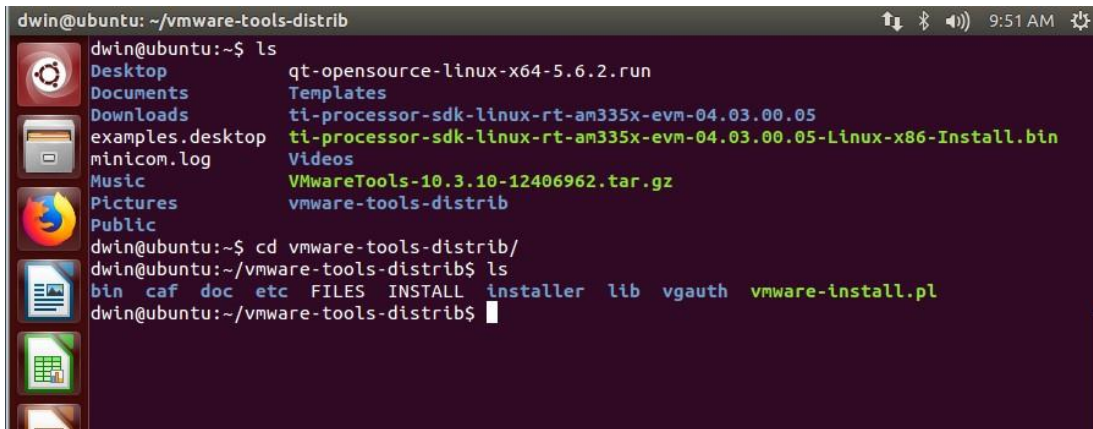
(6) At this point, we need to open the terminal as shown. Click the upper left icon and enter “**Terminal**” and click the “**Terminal**” icon (the terminal can be locked in the taskbar by right-clicking the icon and select “**Lock to Launcher**”). You can also press [Ctrl]+[Alt]+[T] under the root directory to open the terminal.



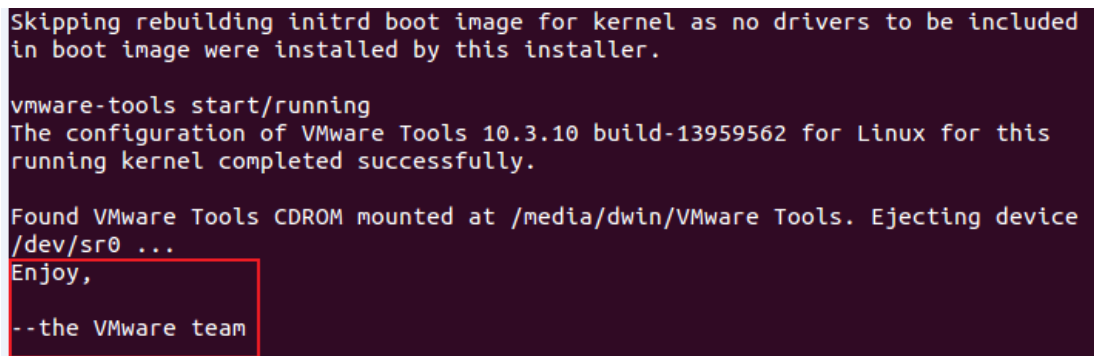
(7) Enter the command to enable the operable privilege: **sudo chmod +x VM** (to display the full name by **Tab** key) (**enter**). (Note: for the first time to use the administrator sudo privilege, you need to enter the password, i.e., the login password, which is not visible when entering.)

```
dwin@ubuntu:~$ sudo chmod +x VMwareTools-10.3.10-13959562.tar.gz
[sudo] password for dwin:
dwin@ubuntu:~$ tar -xvf V
Videos/
VMwareTools-10.3.10-13959562.tar.gz
dwin@ubuntu:~$ tar -xvf VMwareTools-10.3.10-13959562.tar.gz
```

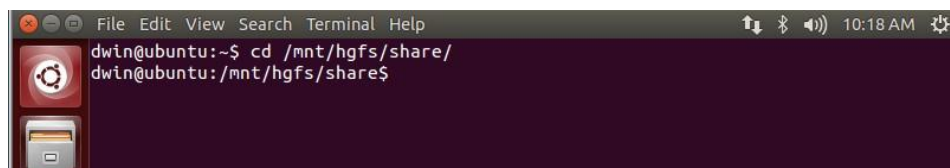

(8) Enter the decompression command: **tar -xvf VM (Tab key) (Enter)**, then it will automatically extract the tar file to the current directory. You can see the decompressed file named “vmware-tools- distrib” in the current directory. Enter the command: **cd vm (Tab key)** (The rest part is omitted).



(9) Enter the operation command: **sudo ./vm (Tab)**, and then the installation will start. When [yes] or [no] appears, just type **yes** and enter for all the following options until the installation is complete as shown.

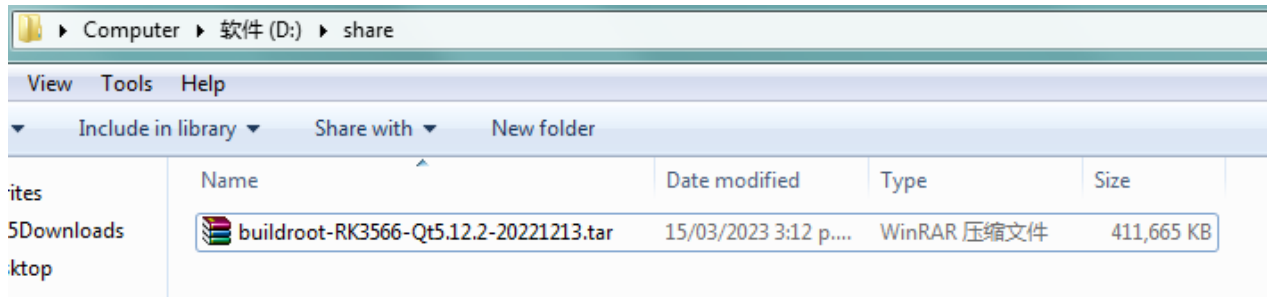


(10) At this time, we can enter the command: **cd /mn (Tab all the way to the shared folder you set)**, the path is /mnt/hgfs/***, and the shared folder is set up here.



2.2 Install RK3566 Toolchain

(1) Use the shared folder or SFTP to move the RK3566 tar file to Ubuntu.



(2) Move the tar file to the root directory (/home/dwin) by shared folder. Enter the command: **sudo mv buildroot-RK3566-Qt5.12.2-20221213.tar ~/**. Wait a while and it will be moved to the root directory.

(3) Enter the command **tar -xvf buildroot-RK3566-Qt5.12.2-20221213.tar** to extract the tar file.

(4) Enter the following command in substance:

2.2.1.1 cd buildroot-RK3566-Qt5.12.2-20221213/

2.2.1.2 source env-setup.sh

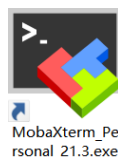
Enter the command **qmake -v** to check the version of qmake and see if the environment is successfully built.

```
dwin@ubuntu:~/buildroot-RK3566-Qt5.12.2-20221213$ source env-setup.sh
dwin@ubuntu:~/buildroot-RK3566-Qt5.12.2-20221213$ qmake -v
QMake version 3.1
Using Qt version 5.12.2 in /home/dwin/buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/lib
```

2.3 Development Board Configuration

2.3.1 Terminal Software

(1) You can download and use either SecureCRT or MobaXterm, and this section will introduce the use of MobaXterm.

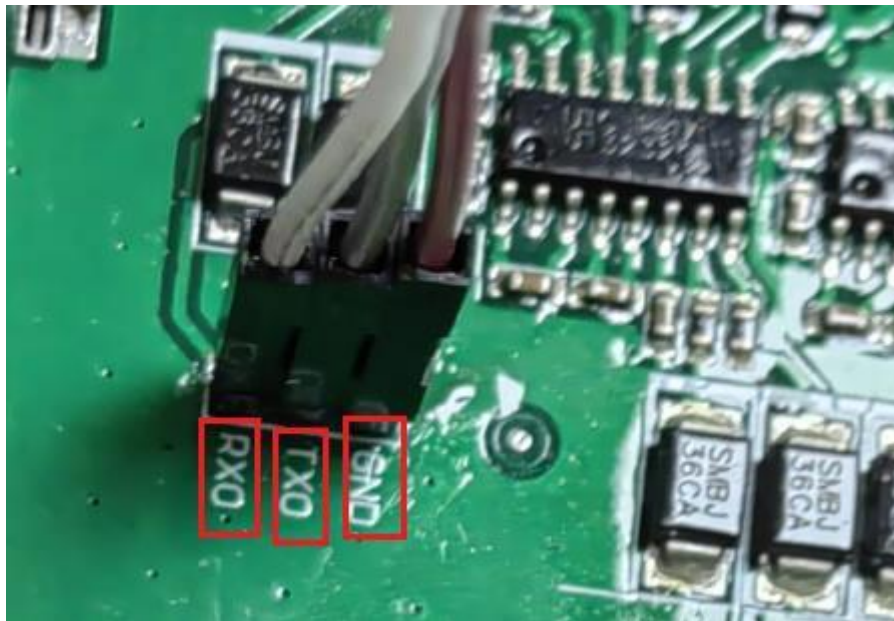
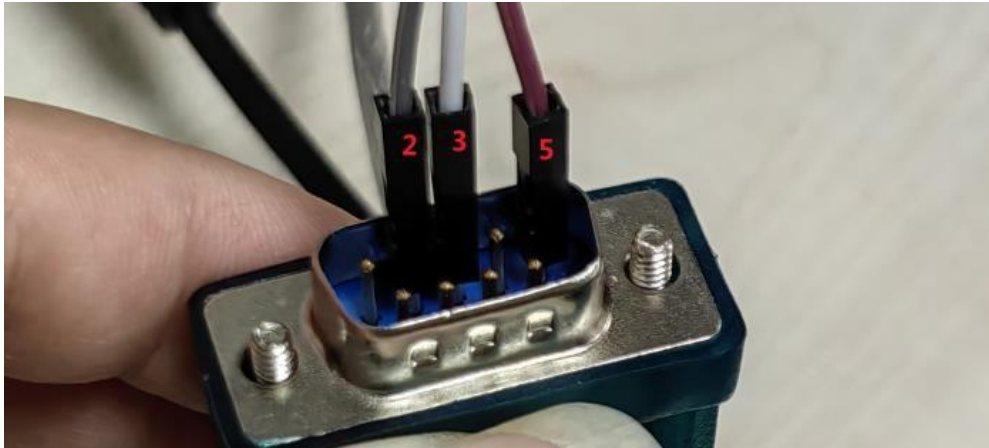


(2) There are two connection options: Serial (UART 0) connection and Telnet connection by a network cable.

2.3.2 Serial Connection

(1) Serial (UART 0) connection. As illustrated in the following pictures, connect No.2 to TX, No.3 to

RX and No.5 to GND. (RS232 as an example here.)

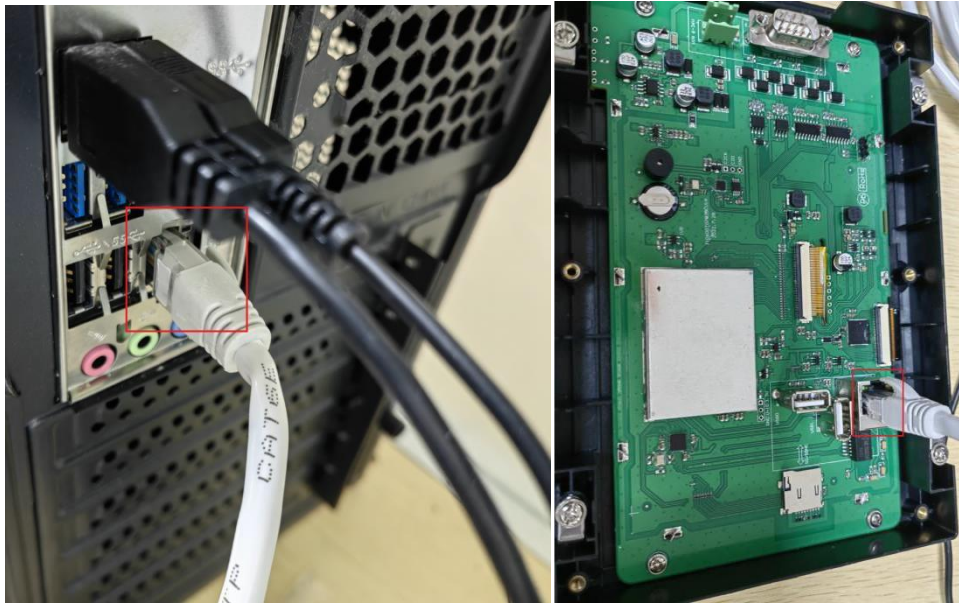


(2) Select [Sessions]-> [New Session]. First, select “serial”. Next, select **serial port** and select **speed**. Last, check the information and click “OK” to finish.

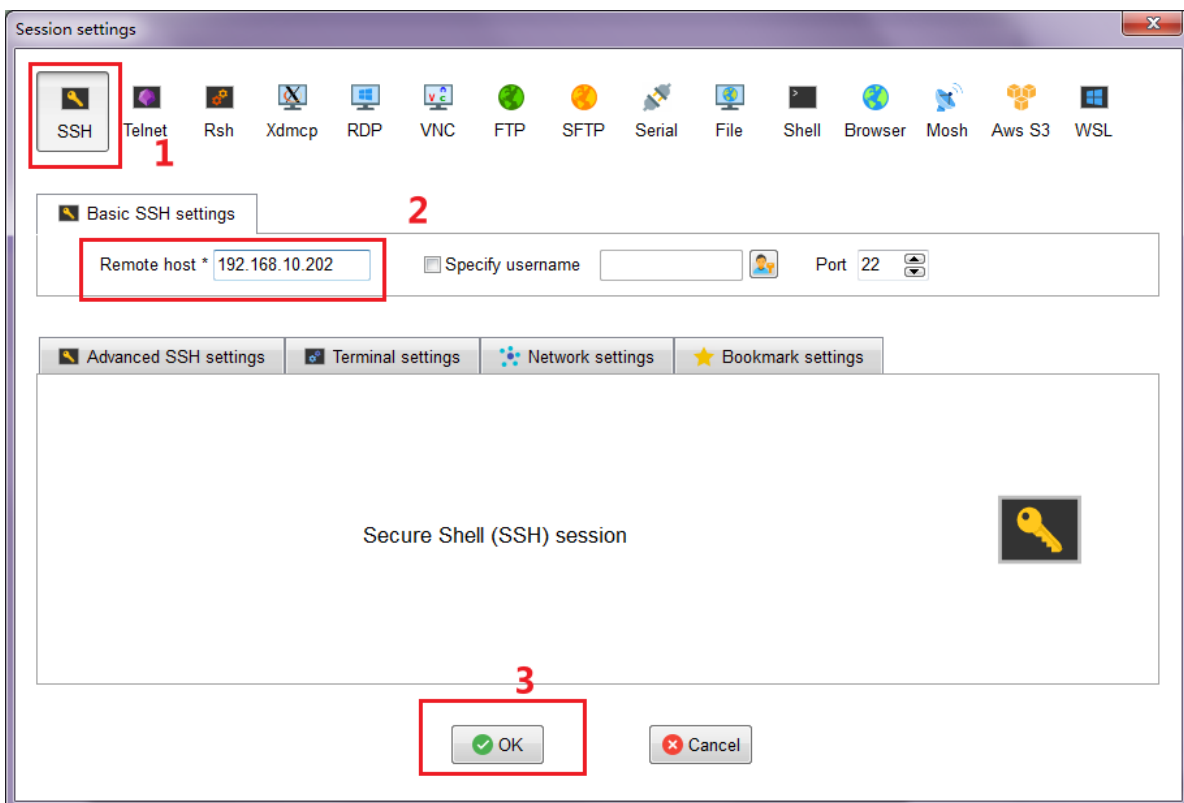
(3) Power up the development board, and enter “root” to start. (Note: If you operate after a while after powering up, there may be no text on the displayed interface, and only a black screen with no boot information. In this case, you only need to enter “root”).

2.3.3 Ethernet SSH Connection

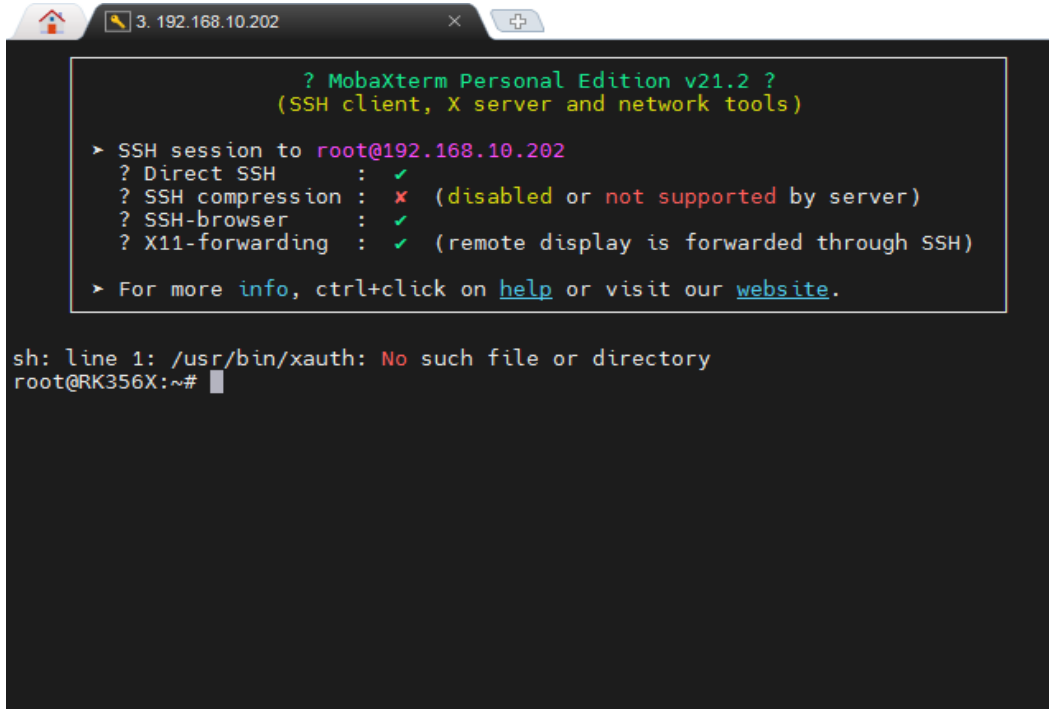
(1) Plug the network cable into the development board network port, and refer the specific notes on the Internet.



(2) First, click “**Session**” and select “**New session**” then select “**SSH**”. Next, enter the IP of the development board and click “**OK**” (Note: the default IP of the development board is: 192.168.10.201 or 192.168.10.202. To achieve communication, the development board should be connected to the same LAN as the computer.



(3) Power on the development board and the following interface is displayed. Enter "root" for the username and "rockchip" for the password to start the operation.



```
? MobaXterm Personal Edition v21.2 ?  
(SSH client, X server and network tools)  
  
> SSH session to root@192.168.10.202  
? Direct SSH : ✓  
? SSH compression : ✗ (disabled or not supported by server)  
? SSH-browser : ✓  
? X11-forwarding : ✓ (remote display is forwarded through SSH)  
  
> For more info, ctrl+click on help or visit our website.  
  
sh: line 1: /usr/bin/xauth: No such file or directory  
root@RK356X:~#
```

2.3.4 Boot the startup logo

The DWIN 40 and 40OS-1 series Linux screens currently do not support user to modify the startup interface LOGO themselves. However, user can provide BMP images for modification by the DWIN R&D team.

3 QT Project Cross-compilation

3.1 Install Qt Creator

3.1.1 System Requirements

This document is based on Ubuntu 14.04 system for verification. Other versions of Ubuntu systems should work but are not verified.

3.1.2 Download Qt Creator

The version of Qt Creator used in this document is 2.7.2. Please download the version that matches the operating system.

| | | | |
|--|-------------------|-----|-------------------------|
|  source/ | 02-Jul-2013 19:43 | - | |
|  qt-creator-windows-opensource-2.7.2.exe | 02-Jul-2013 19:43 | 53M | Details |
|  qt-creator-mac-opensource-2.7.2.dmg | 02-Jul-2013 19:43 | 53M | Details |
|  qt-creator-linux-x86_64-opensource-2.7.2.bin | 02-Jul-2013 19:43 | 62M | Details |
|  qt-creator-linux-x86-opensource-2.7.2.bin | 02-Jul-2013 19:43 | 63M | Details |
|  qt-creator-2.7.2-src.zip | 02-Jul-2013 19:43 | 27M | Details |
|  qt-creator-2.7.2-src.tar.gz | 02-Jul-2013 19:43 | 22M | Details |

3.1.3 Install Qt Creator

Copy the installer to your Ubuntu system and add execute permissions to the file:

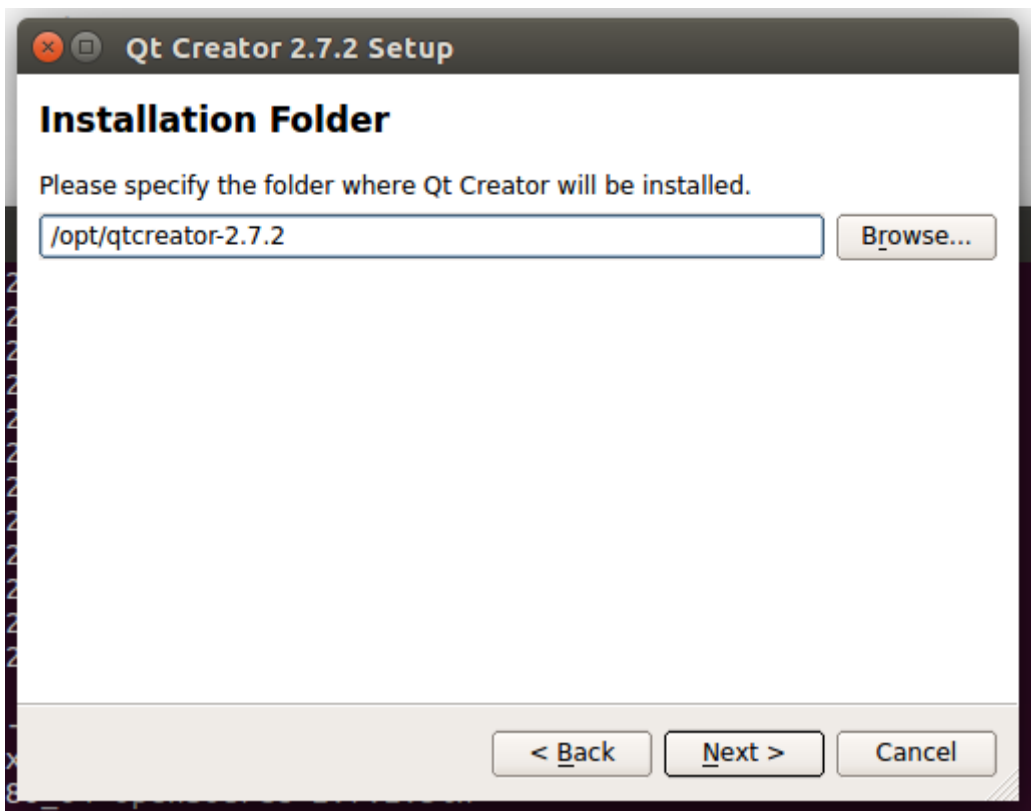
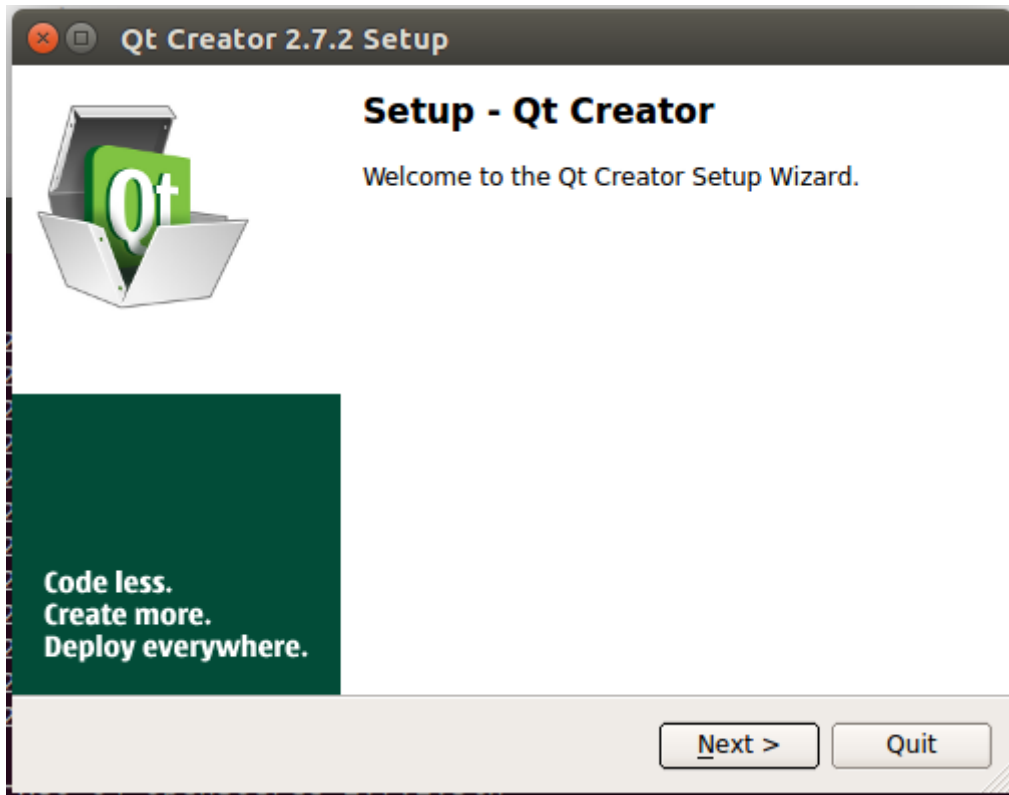
```
# chmod +x qt-creator-linux-x86_64-opensource-2.7.2.bin
```

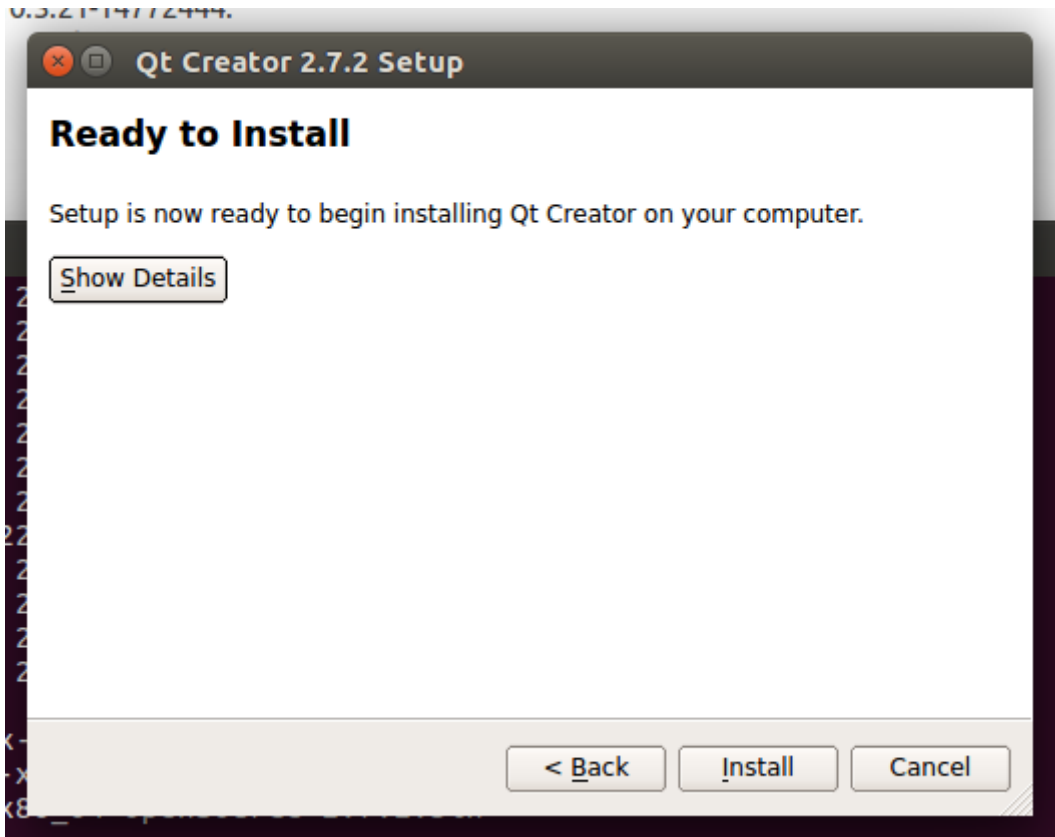
```
dwin@ubuntu:~$ cd /home/dwin
dwin@ubuntu:~$ chmod +x qt-creator-linux-x86_64-opensource-2.7.2.bin
```

Run the installer

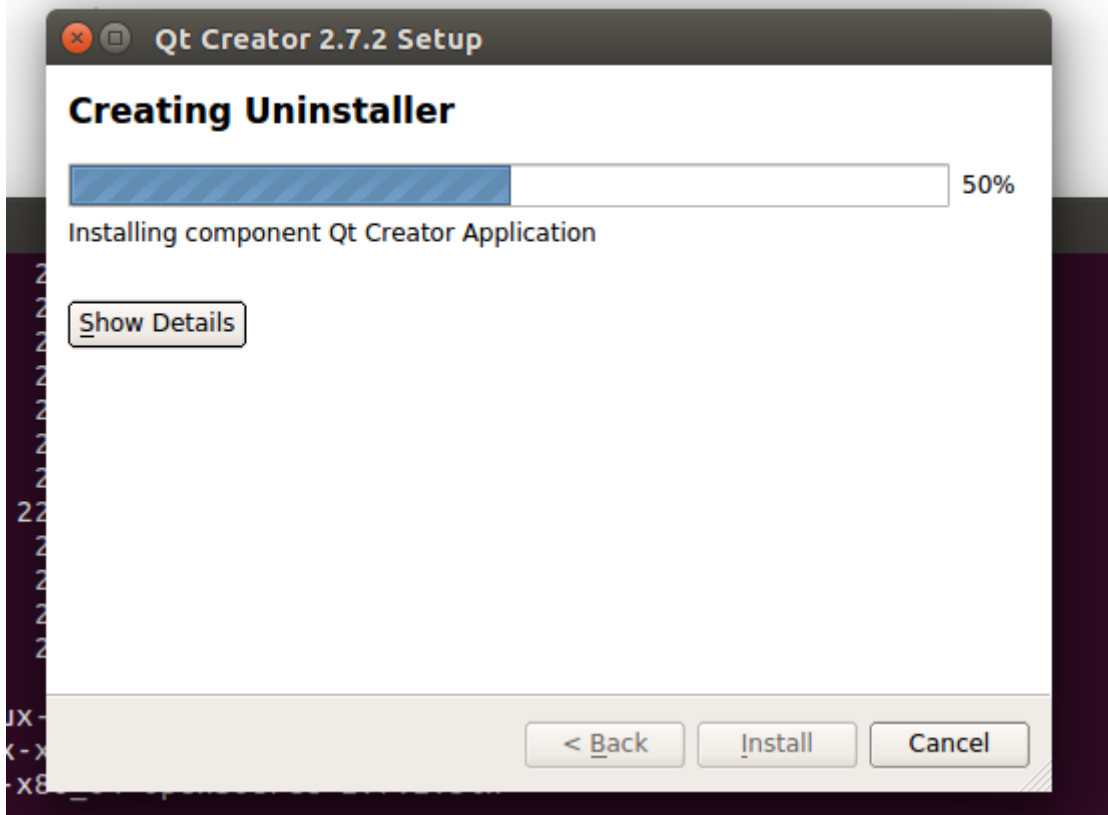
```
# sudo ./qt-creator-linux-x86_64-opensource-2.7.2.bi
```

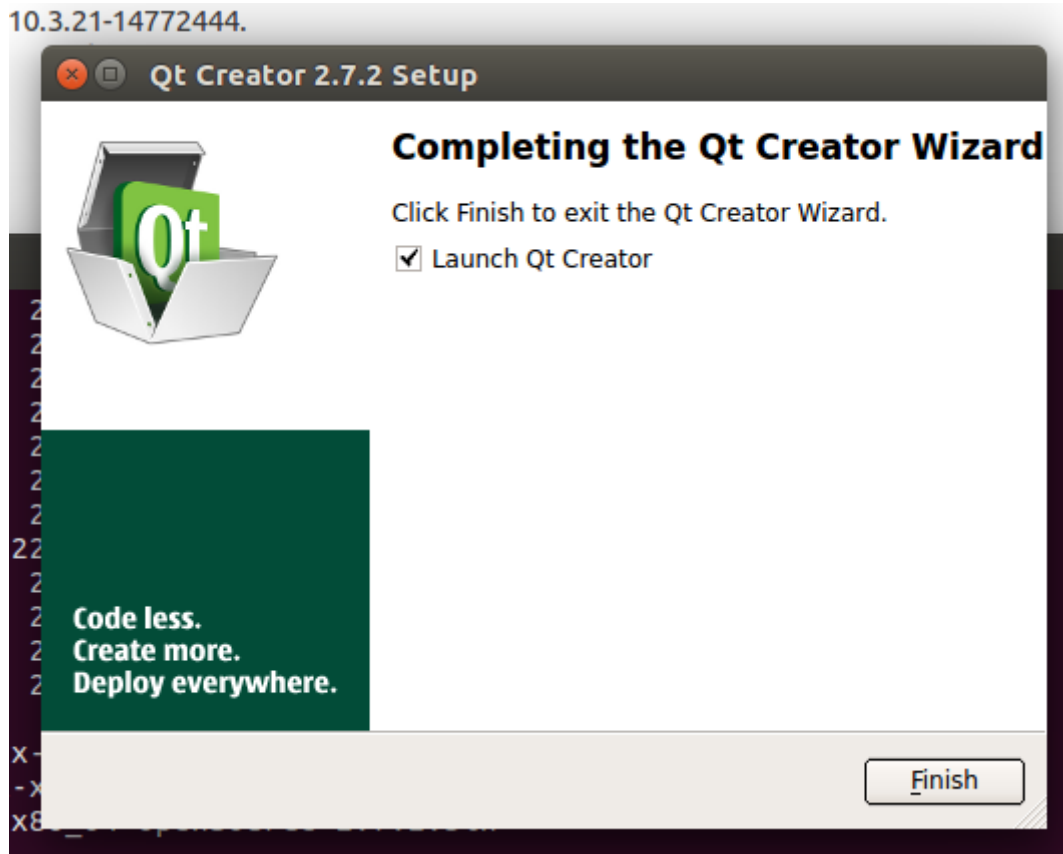
Click the “Next”:





10.3.21-14772444.



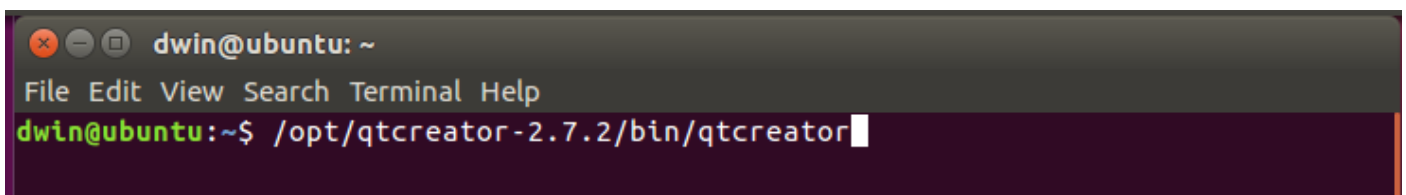


3.2 Set up the cross-compilation environment

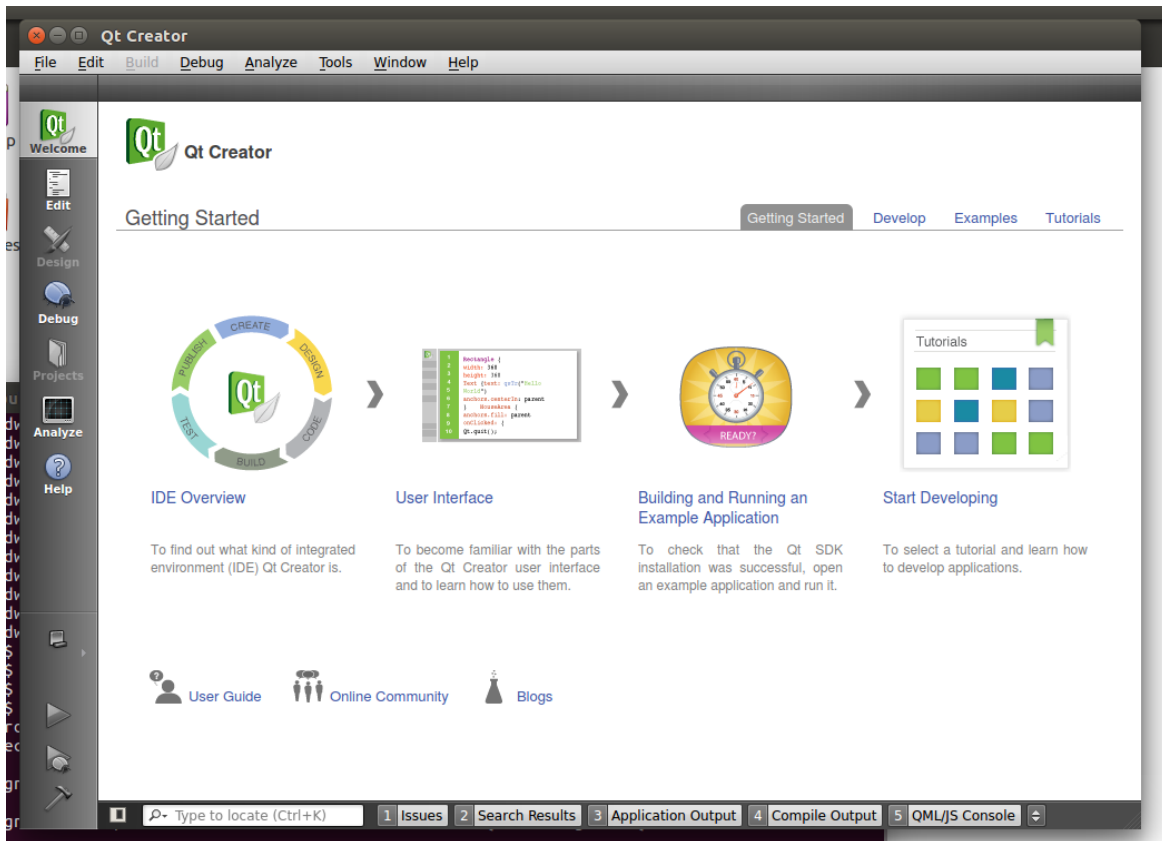
3.2.1 Run the Qt Creator

The Qt Creator executable file is in the bin directory of the installation directory.

```
# /opt/qtcreator-2.7.2/bin/qtcreator
```

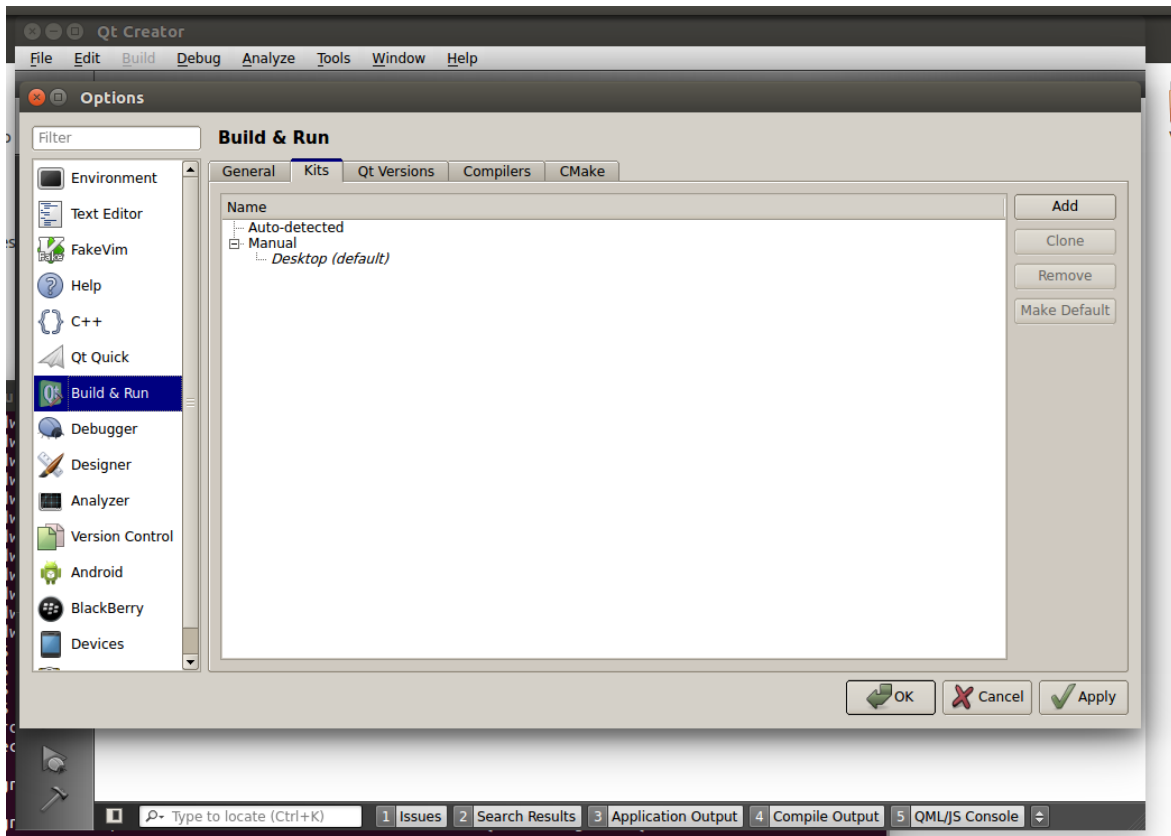
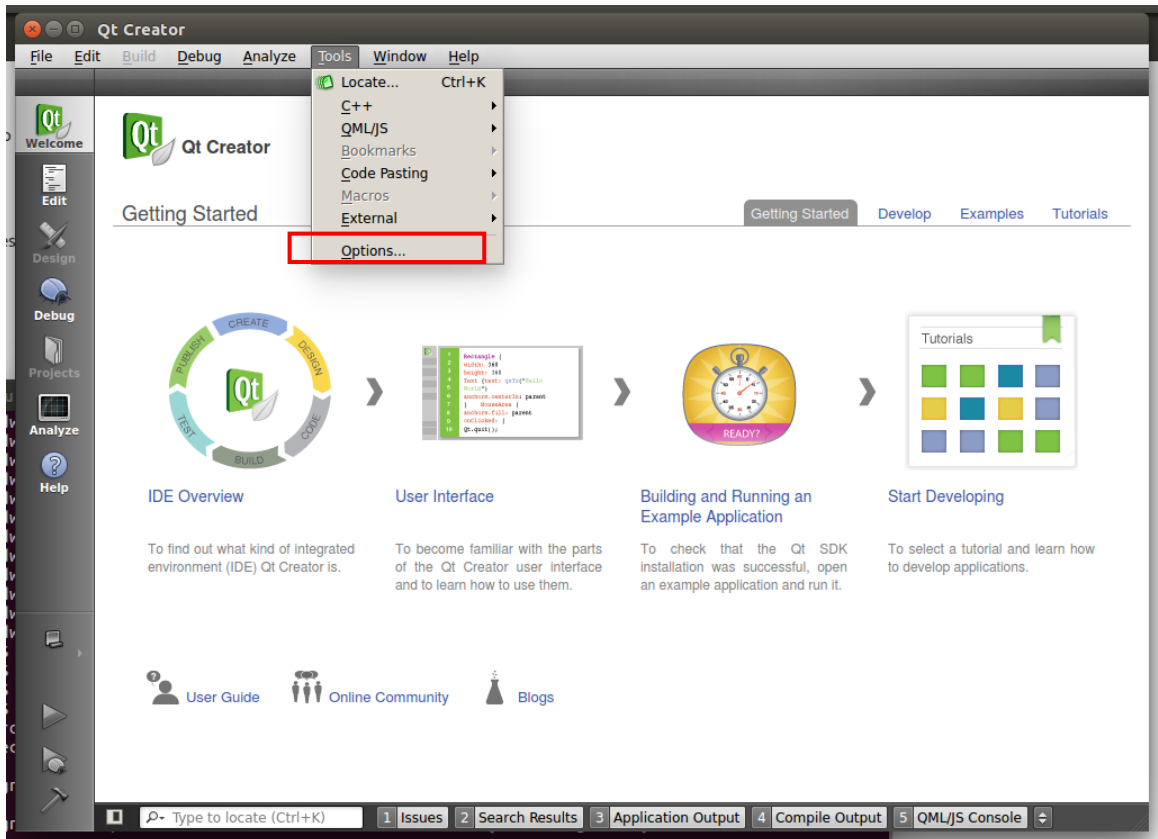


The interface of software is as below.



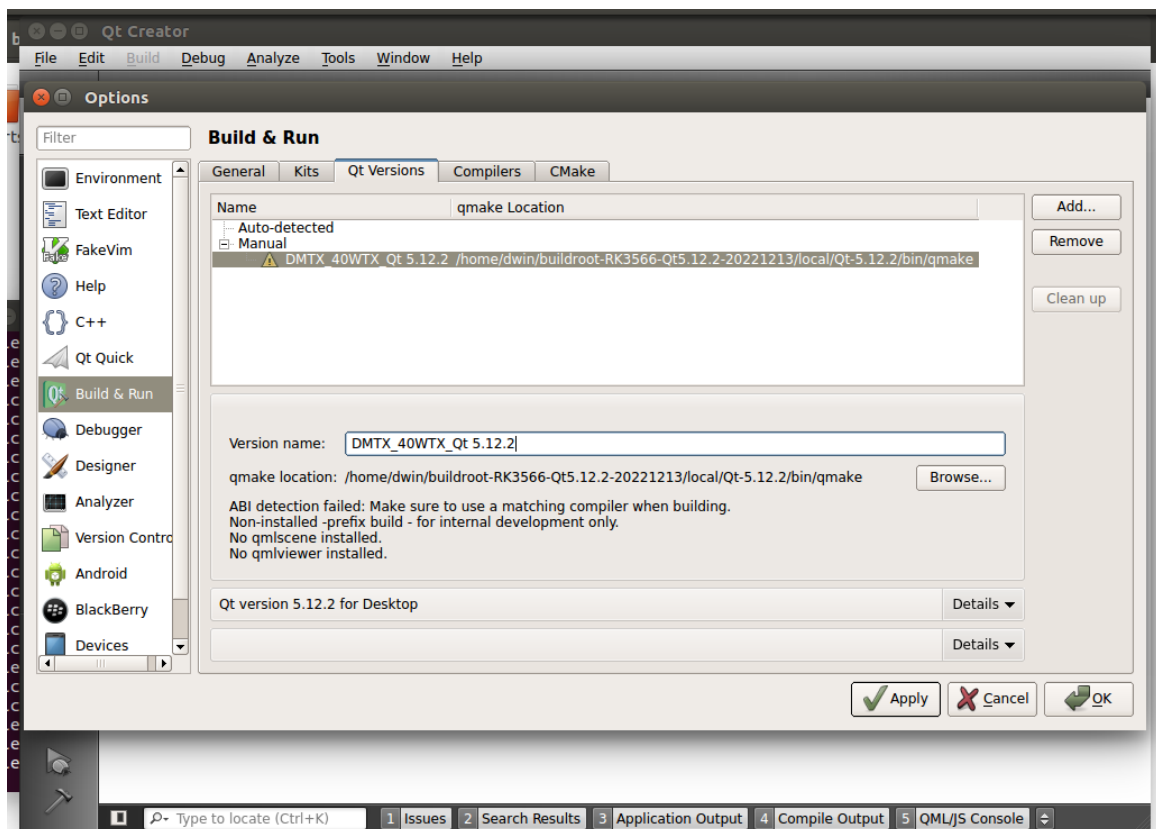
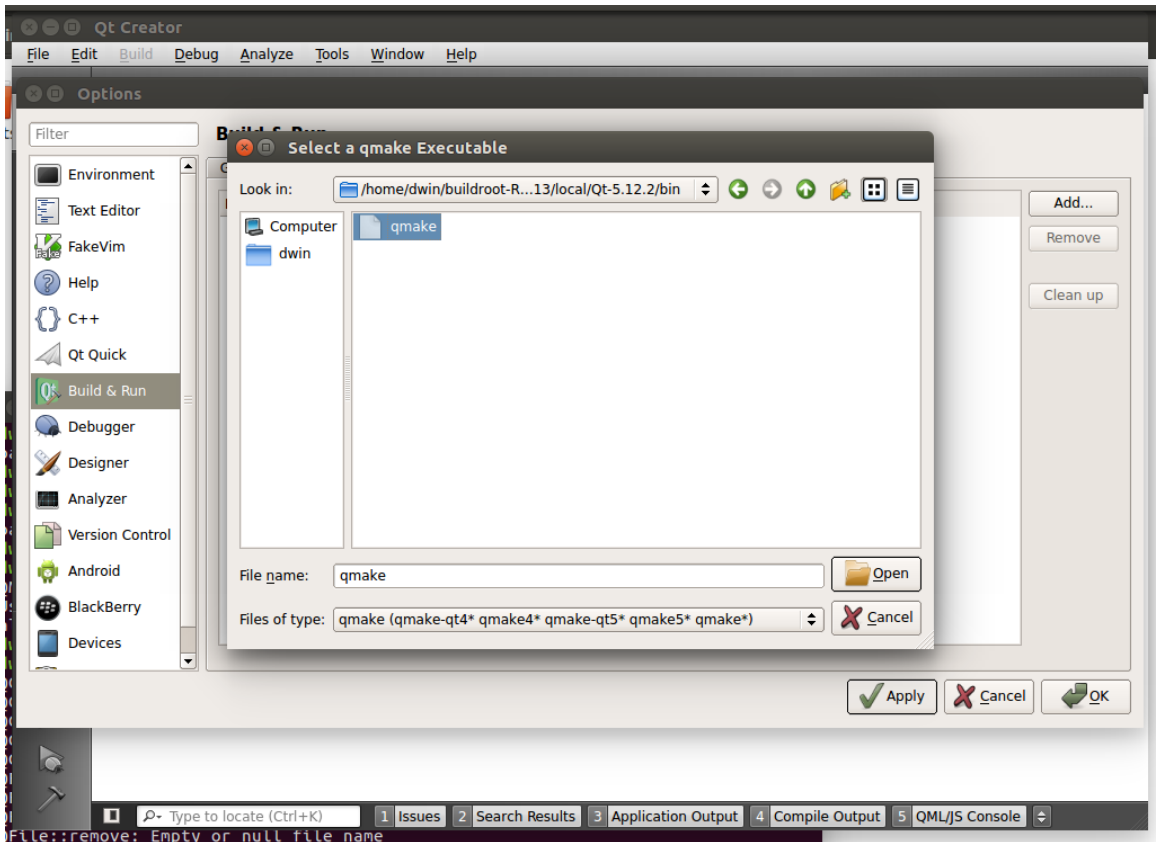
3.2.2 Set up the cross-compilation environment

Choose [tool] – [options] as below.

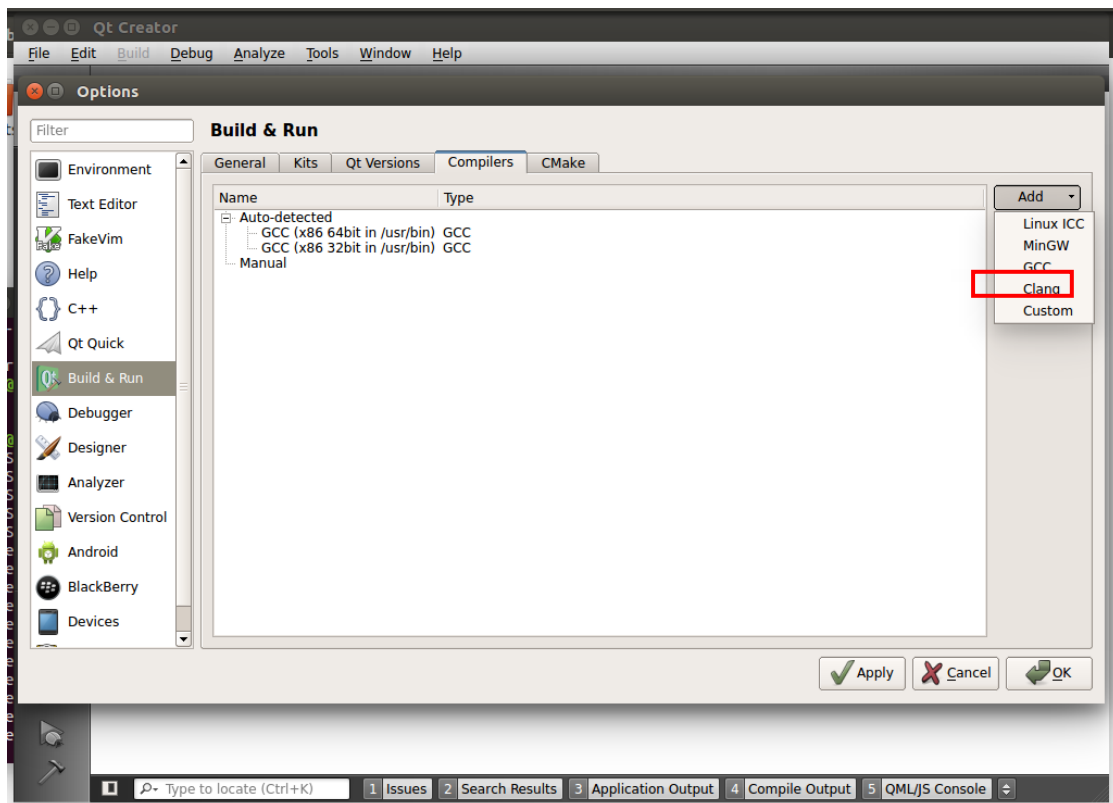


Set qmake: choose [Build & Run] – [Qt Version] – [Add],

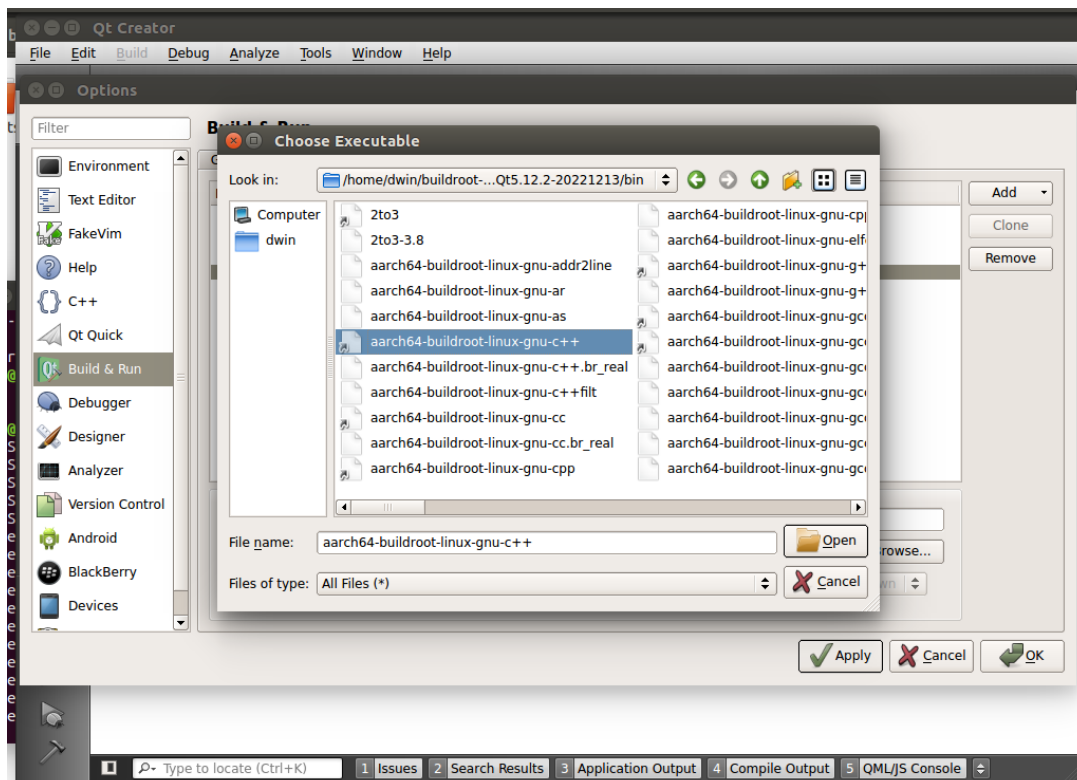
“qmake” is in the ‘local/Qt-5.12.2/bin/’ directory of buildroot-RK3566-Qt5.12.2-20221213.tar.gz

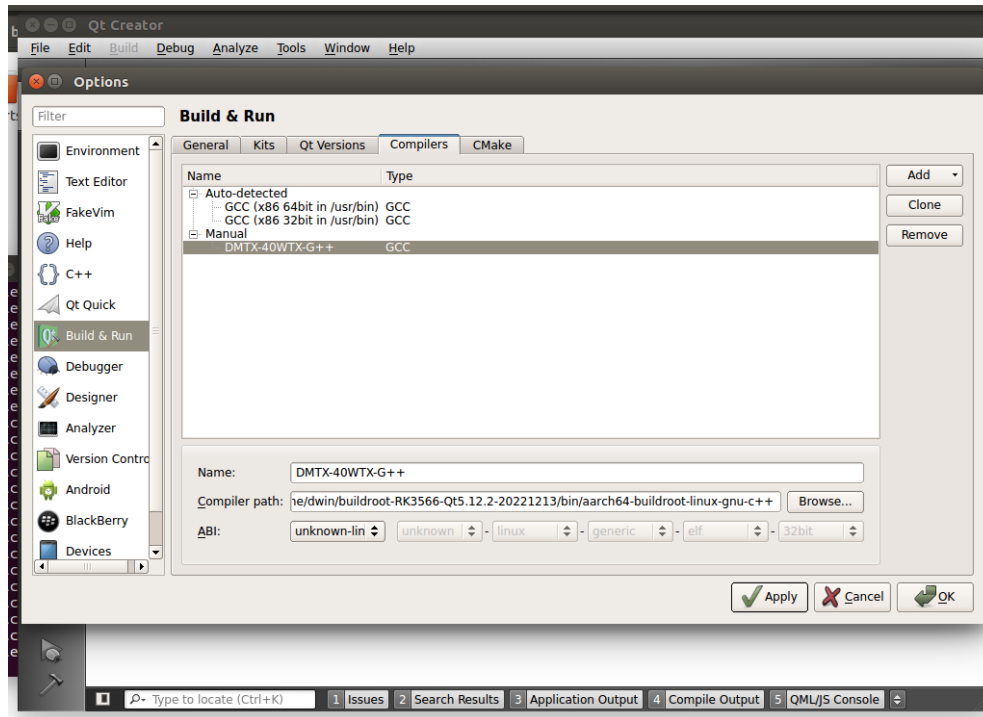


Set compilation toolchain: choose [Build & Run] – [Compilers] – [Add] – [GCC]:

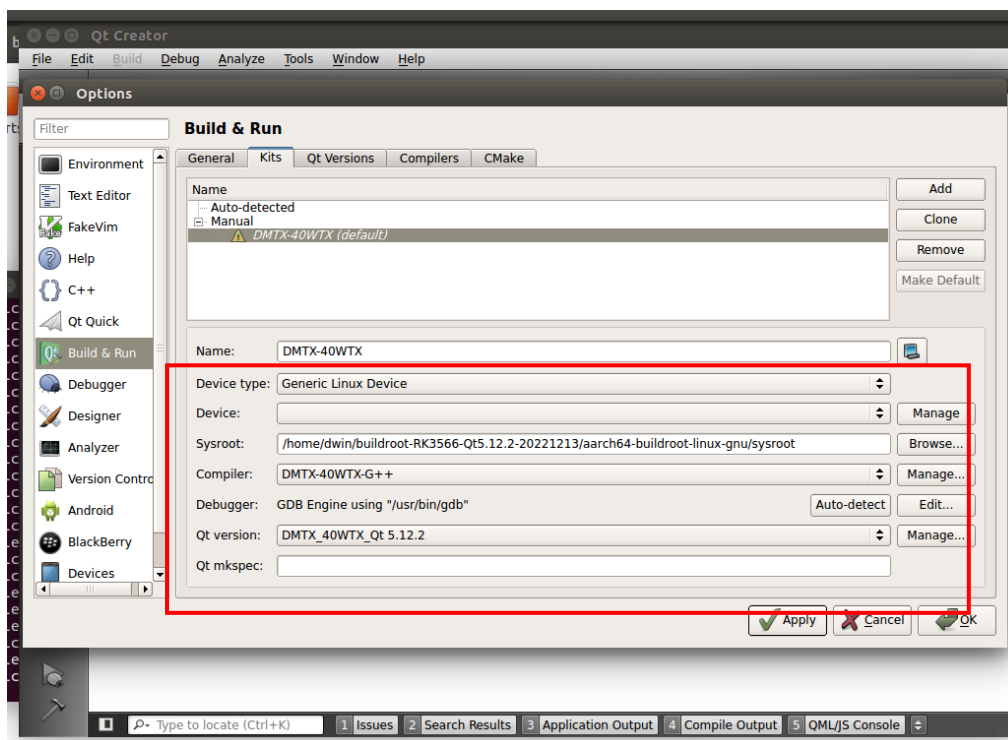


The compiler is located in the 'bin' directory of the 'buildroot-RK3566-Qt5.12.2-20221213.tar.gz' package.





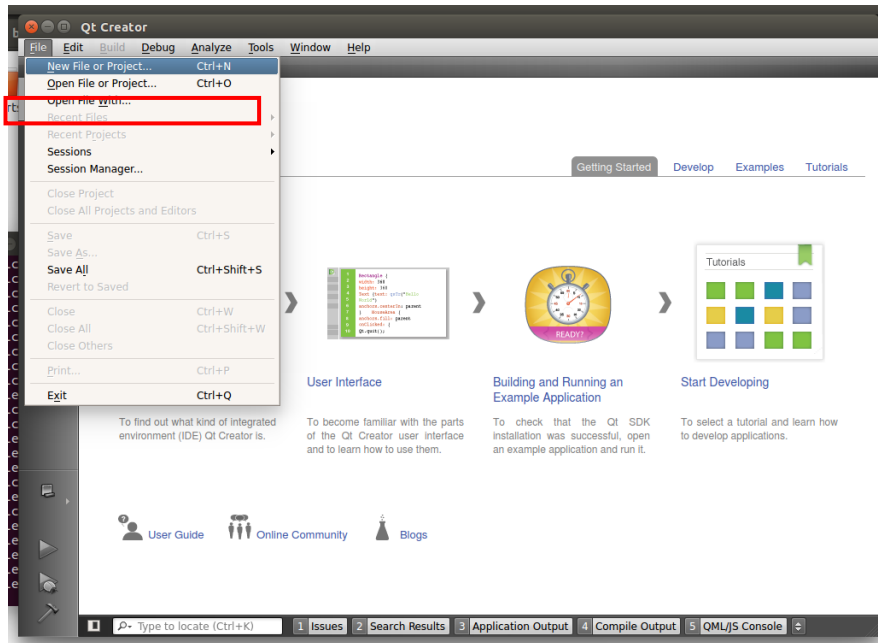
Set up the build kit: choose [Build & Run] – [Kits]:



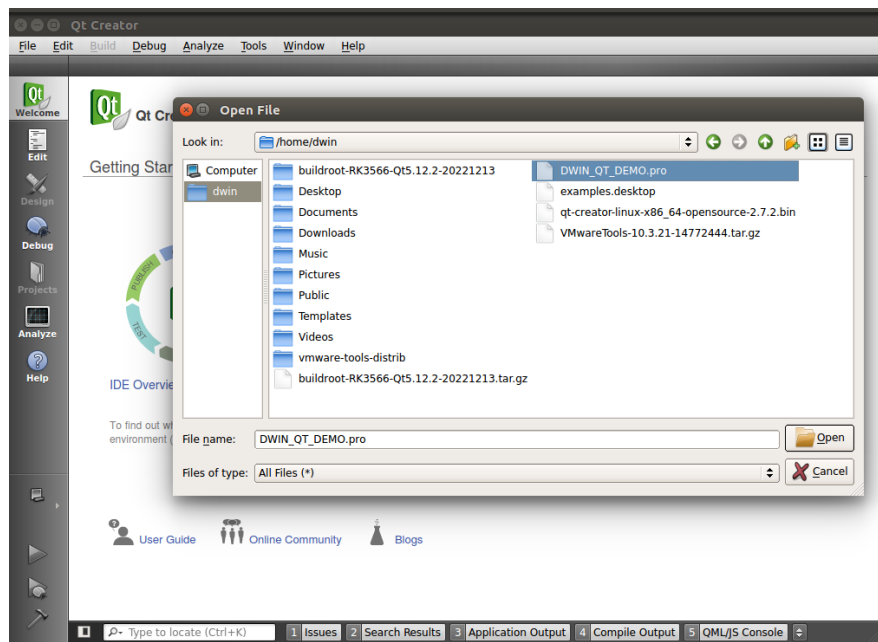
3.3 Compile Qt project

3.3.1 Open the project

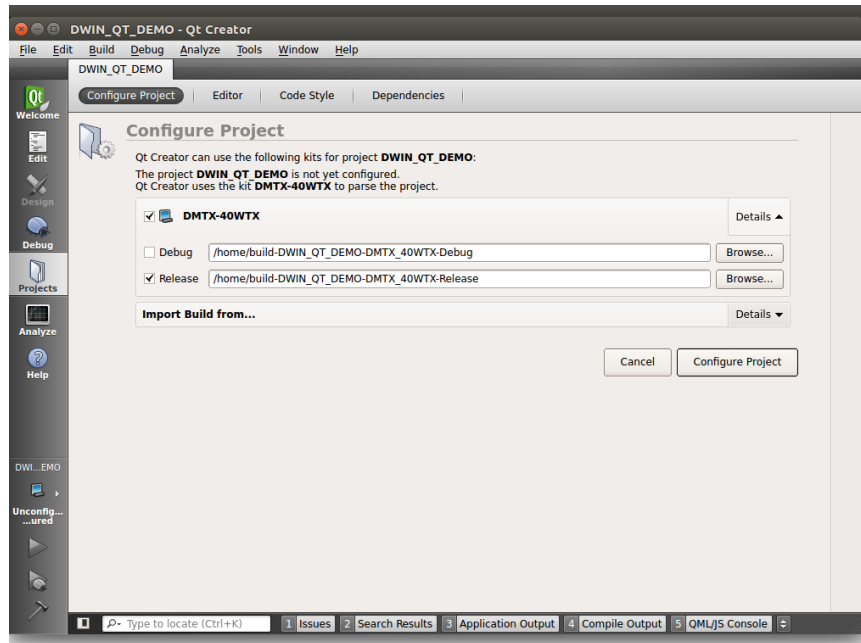
[File] – [open file or project]:



Choose the Qt project:



Configure the project:



3.3.2 Add environment variables

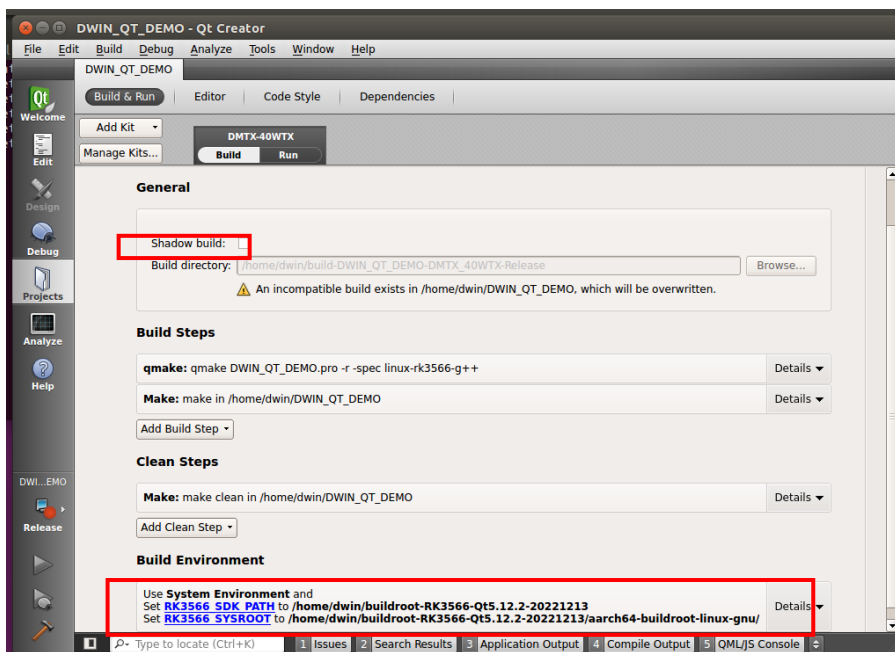
Go to [Projects] – [Build & Run] – [Build Environment], and add a variable:

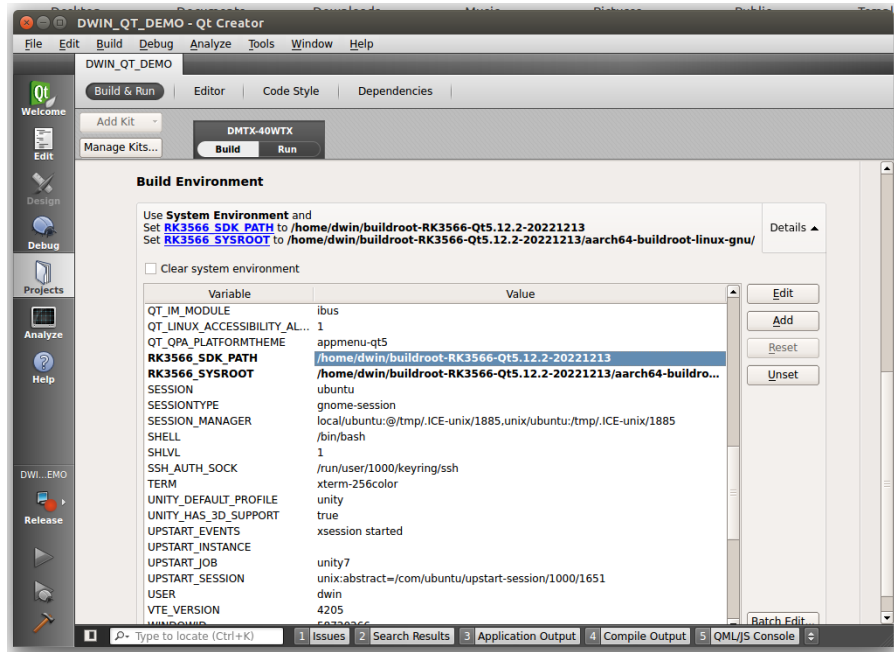
Variable Name 1: RK3566_SDK_PATH

Value 1: Root directory of the 'buildroot-RK3566-Qt5.12.2-20221213.tar.gz' package

Variable Name 2: RK3566_SYSROOT

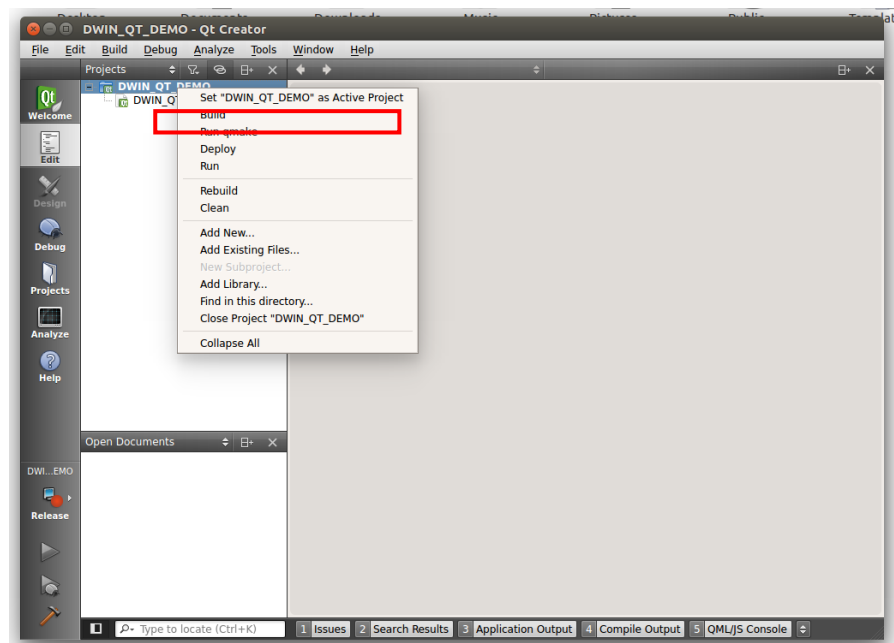
Value 2: 'sysroot' directory in the 'aarch64-buildroot-linux-gnu' directory of the 'buildroot-RK3566-Qt5.12.2-20221213.tar.gz' package.



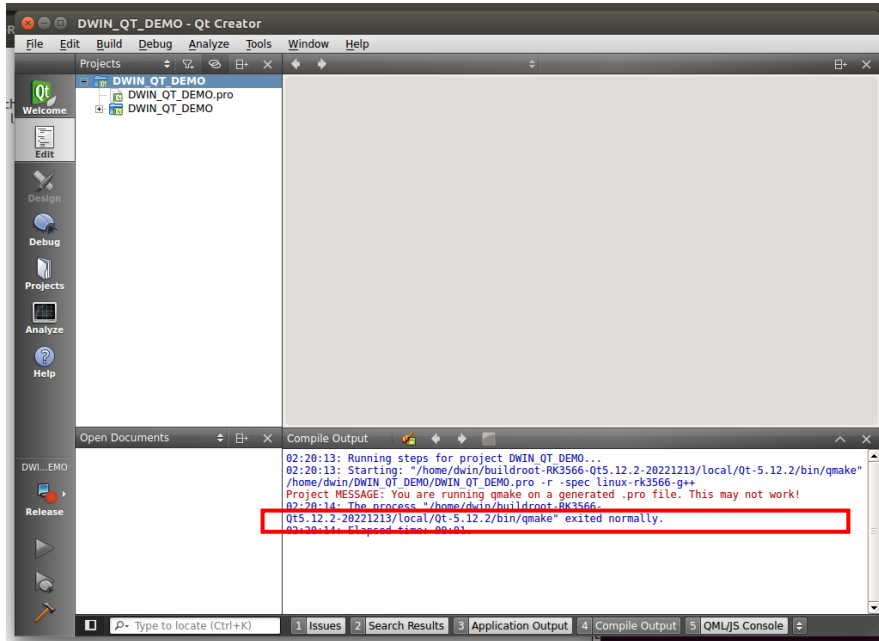


3.3.3 Run qmake

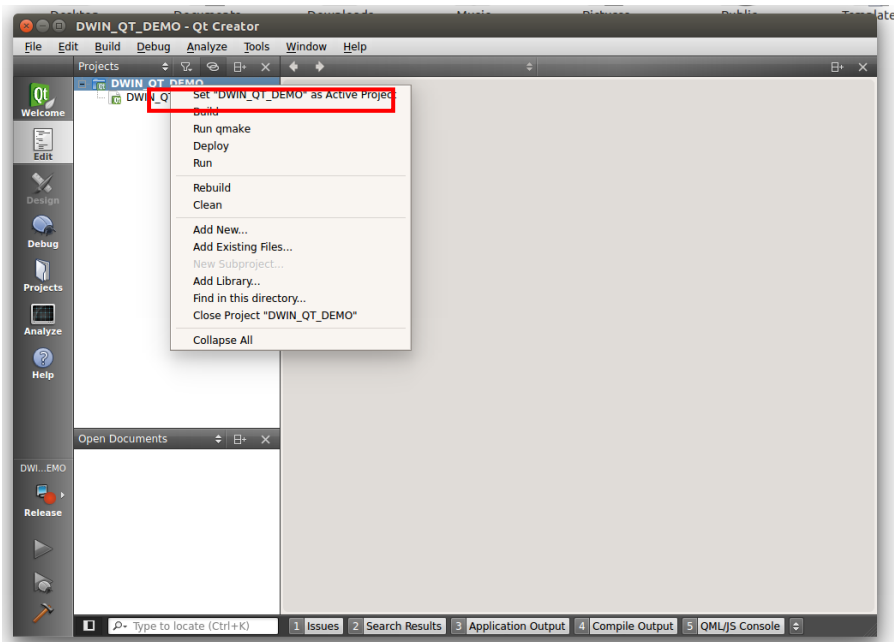
Choose project, 'right key' – run qmake



When qmake is successful, it looks like the image below (the red part is the printout of DWIN_QT_DEMO.pri, which does not affect).



3.3.4 Build





(2) Enter the command: **make**, and then a binary file named after the project will be generated. But the file cannot be run in Ubuntu, so you need to download it to the development board. You can refer to [2.2](#).

```

dwin@ubuntu: ~/DWIN_QT_DEMO
dwin@ubuntu:~/DWIN_QT_DEMO$ qmake -v
QMake version 3.1
Using Qt version 5.12.2 in /home/dwin/buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/lib
dwin@ubuntu:~/DWIN_QT_DEMO$ ls
DWIN_QT_DEMO.pro DWIN_QT_DEMO.pro Resources Source
dwin@ubuntu:~/DWIN_QT_DEMO$ qmake
Info: creating stash file /home/dwin/DWIN_QT_DEMO/.qmake.stash
Project MESSAGE: You are running qmake on a generated .pro file. This may not work!
dwin@ubuntu:~/DWIN_QT_DEMO$ ls
DWIN_QT_DEMO.pro DWIN_QT_DEMO.pro Makefile Resources Source
dwin@ubuntu:~/DWIN_QT_DEMO$ make
aarch64-buildroot-linux-gnu-g++ -C -pipe --sysroot=/home/dwin/buildroot-RK3566-Qt5.12.2-20221213/aarch64-buildroot-linux-gnu/sysroot -O2 -Wall -W -D_REENTRANT -fPIC -DQT_NO_DEBUG -DQT_WIDGETS_LIB -DQT_GUI_LIB -DQT_SERIALPORT_LIB -DQT_SQL_LIB -DQT_CORE_LIB -I. -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/include -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/include/QtWidgets -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/include/QtGui -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/include/QtSerialPort -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/include/QtSql -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/include/QtCore -I../buildroot-RK3566-Qt5.12.2-20221213/aarch64-buildroot-linux-gnu/sysroot/usr/include/libdrm -I../buildroot-RK3566-Qt5.12.2-20221213/usr/local/Qt-5.12.2/mkspecs/linux

```

```

20221213/aarch64-buildroot-linux-gnu/sysroot/usr/lib/./lib64/libffi.so /home/dwin/buildroot-RK3566-Qt5.12.2-20221213/aarch64-buildroot-linux-gnu/sysroot/usr/lib/./lib64/librt.a /home/dwin/buildroot-RK3566-Qt5.12.2-20221213/aarch64-buildroot-linux-gnu/sysroot/usr/lib/./lib64/libffi.so -lpthread
dwin@ubuntu:~/DWIN_QT_DEMO$ ls
dwinatdemo          moc_toolbody.o          qrc_DWIN_QT_DEMO.o
DWIN_QT_DEMO.pro   moc_toolcomtest.cpp    Resources
DWIN_QT_DEMO.pro   moc_toolcomtest.o      Source
main.o              moc_toolheader.cpp     toolbasetest.o
mainwindow.o       moc_toolheader.o       toolbody.o
Makefile            moc_toolsqltest.cpp    toolcomtest.o
moc_mainwindow.cpp moc_toolsqltest.o      toolheader.o
moc_mainwindow.o   moc_toolstartpage.cpp  toolsqltest.o
moc_predefs.h       moc_toolstartpage.o    toolstartpage.o
moc_toolbasetest.cpp moc_tooltouchtest.cpp  tooltouchtest.o
moc_toolbasetest.o moc_tooltouchtest.o    tooltranslator.o
moc_toolbody.cpp   qrc_DWIN_QT_DEMO.cpp   toolutility.o
dwin@ubuntu:~/DWIN_QT_DEMO$

```

3.5 USB Download

- (1) Put the cross-compiled files in the shared folder, you can copy the files using the command: **cp (file name) (the path of shared folder)**, i.e., **cp dwinqtdemo /mnt/hgfs/share/**
- (2) Move the target file in the shared folder from the computer to the USB/SD card.
- (3) Insert the USB into the development board.
- (4) Open MobaXterm and connect. Enter the command: **cd /mnt/usb** to open the “usb” folder and select “sdax” folder. Copy or move the target file to the target directory (you can customize the folder to avoid clutter) using the command: **cp (target file)(folder)**, i.e. **cp dwinqtdemo /usr/bin/**.

3.6 Run the Dwinqtdemo Program

Configuration file should be modified to run the demo.

Enter the command: **vi /etc/init.d/runqt(enter)** and move the cursor to the beginning of the “qttesttool” line. Press **i** to enter insert mode. Input “#” to comment out this line. Move the cursor to the end of this line and press enter. Input the absolute path of dwinqtdemo+ a blank space +&. Then press Esc to exit insert mode. Enter “: wq” to save the modification.

```
#!/bin/bash
vnclinuxfb_conf=/etc/vnclinuxfb.conf

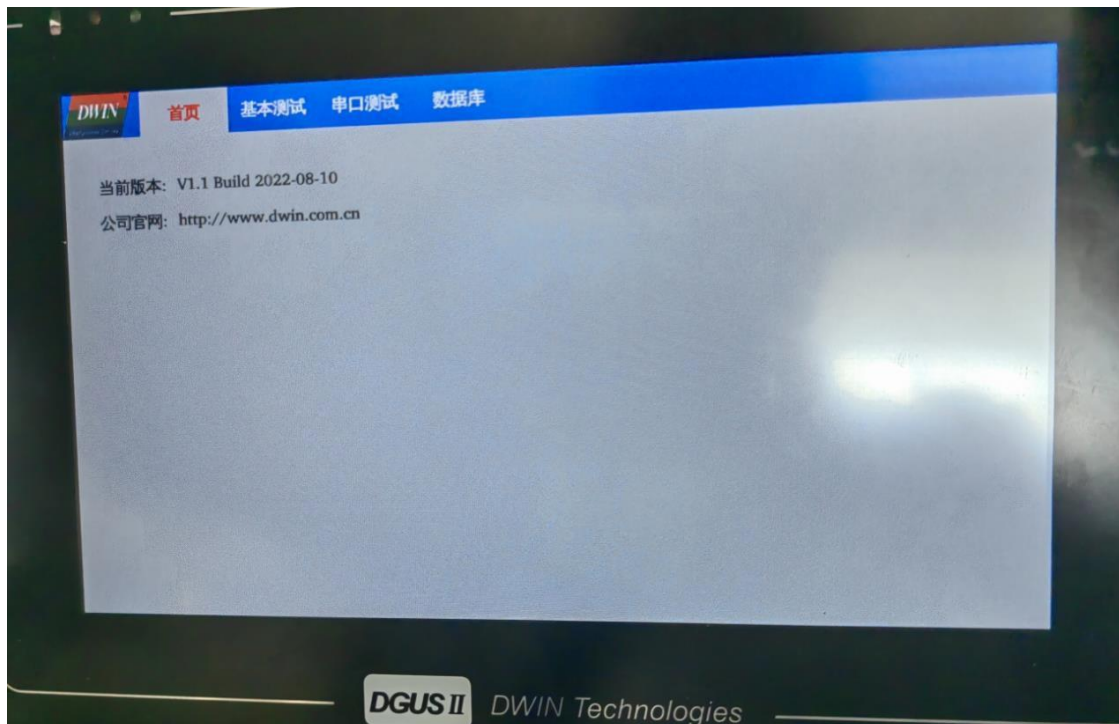
vnclinuxfb_enable=`awk -F '=' '{a=1}a==1&&$1~/enable/{gsub(/[[[:blank:]]*/,"",$2);

if [ $vnclinuxfb_enable == "1" ]; then
    export QT_QPA_PLATFORM="vnclinuxfb:fb=/dev/fb0:rotation=0"
else
    export QT_QPA_PLATFORM="linuxfb:fb=/dev/fb0:rotation=0"
fi

#qttesttool &
/usr/bin/dwinqtdemo &
if [ $vnclinuxfb_enable == "1" ]; then
    /etc/init.d/runfrpc &
fi
~
~
~
~
~
~
~
~
~
~
I runqt [Modified] 13/15 86%
```

You can run the demo using the command “./runqt”.

```
# cd /etc/init.d/  
# ./run  
runhmi      runqt      runupdate  
# ./runqt
```



3.7 Network Connection

Brightness adjustment, buzzer, and system time setting for the 40 series are Linux universal interfaces.

To check the current brightness:

```
cat /sys/class/backlight/backlight/brightness
```

Config the backlight to 0 (display off):

```
echo 0 > /sys/class/backlight/backlight/brightness
```

Config the backlight to 200:

```
echo 200 > /sys/class/backlight/backlight/brightness
```

3.8 System time setting

```
date -s "2023-03-01 11:07:09"
```

```
hwclock -w
```

4 Set up the build environment

4.1 The build environment of Linux SDK

Note:

(1) It is recommended to develop in the Ubuntu 18.04 system environment. If other system versions are used, the build environment may need to be adjusted accordingly.

(2) Compile with normal user, do not compile with root user authority.

4.1.1 Download SDK

First prepare an empty folder to place SDK, better under home, here we use `~/proj` as example.

Attention: To avoid unnecessary errors, please do not place/unzip the SDK in VM shared folders or non-english directories.

Install a few software packages before getting SDK:

```
sudo apt update  
sudo apt install -y repo git python
```

Using the command `repo` requires a higher network standard. Choose whether to use it.

Get full SDK options:

Please kindly note: contact sales to get the account and password of DWIN server, then submit the key.

```
mkdir ~/proj/rk356x_linux_release_v1.3.0b_20221213/  
cd ~/proj/rk356x_linux_release_v1.3.0b_20221213/  
  
## full SDK
```

Successful

```
repo init -u ssh://dwin@192.168.10.107:/work/gitwork/platform/rk3566_linux/manifest.git --repo-url
ssh://dwin@192.168.10.107:/work/gitwork/platform/rk3566_linux/repo.git
```

4.1.2 Sync Code

Execute the following command to synchronize the code:

```
# enter the SDK root directory

cd ~/proj/rk356x_linux_release_v1.3.0b_20221213/

# sync

.repo/repo/repo sync -c

.repo/repo/repo sync -c --no-tags

.repo/repo/repo start firefly --all
```

You can use the following command to update the SDK later:

```
.repo/repo/repo sync -c --no-tags
```

Probably due to the unstable network environment, **.repo/repo/repo sync -c --no-tags** may fail to update.

You can execute it repeatedly.

4.1.3 Directory

```
.
├─ app
├─ buildroot # Buildroot root filesystem build directory
├─ build.sh -> device/rockchip/common/build.sh # compile script
├─ debian # Debian root filesystem compilation directory
├─ device # Compile related configuration files
├─ docs # Documentation
├─ envsetup.sh -> buildroot/build/envsetup.sh
```


Successful

```
|─ external
|─ kernel # Kernel
|─ Makefile -> buildroot/build/Makefile
|─ mkfirmware.sh -> device/rockchip/common/mkfirmware.sh # Link script
|─ prebuilts # Cross compilation toolchain
|─ rkbin
|─ rkflash.sh -> device/rockchip/common/rkflash.sh # Flash script
|─ tools # Tools directory
└─ u-boot #U-Boot
```

4.1.4 Install Dependencies

Install directly on PC:

```
sudo apt-get install repo git ssh make gcc libssl-dev liblz4-tool \  
expect g++ patchelf chrpath gawk texinfo chrpath diffstat binfmt-support \  
qemu-user-static live-build bison flex fakeroot cmake \  
unzip device-tree-compiler python-pip ncurses-dev python-pyelftools
```

4.2 Compile Debian Firmware

This chapter introduces the compilation process of Debian firmware. It is recommended to develop under Ubuntu 18.04 system environment. If you use other system versions, you may need to adjust the compilation environment accordingly.

4.2.1 Compile SDK

4.2.1.1 Configuration before compilation

In the **device/rockchip/rk356x/** directory, there are configuration files of different board types.

Return to SDK root directory and execute build.sh to select the configuration file:

```
./build.sh BoardConfig-rk3566-dwin.mk
```

The configuration file will be linked to **device/rockchip/.BoardConfig.mk**, check the file to verify whether the configuration is successful.

4.2.1.2 Debian root filesystem

Change to the root filesystem directory:

```
cd debian  
./build.sh
```

Create a link and link the filesystem to **linaro-rootfs.img**:

```
cd ..  
ln -rsf debian/linaro-rootfs.img rockdev/rootfs.img
```

4.2.1.3 Automatic compilation

Fully automatic compilation will perform all compilation and packaging operations to generate complete RK firmware.

```
./build.sh
```

4.2.1.4 Partial compilation

- Compile u-boot

```
./build.sh uboot
```

- Compile kernel

```
./build.sh kernel
```

- Compile recovery

```
./build.sh recovery
```

4.2.1.5 Update link

Update each part of the mirror link to **rockdev/** directory:

```
./build.sh firmware
```

4.2.1.6 Package the firmware

Pack the firmware, the generated complete firmware will be saved to the **rockdev/pack/** directory.

RK firmware is the firmware packaged in Rockchip's proprietary format, and can be flashed to eMMC or SD card with the tools provided by Rockchip.

```
./build.sh updateimg
```

4.3 Compile Buildroot firmware

This chapter introduces the compilation process of Buildroot firmware. It is recommended to develop in the Ubuntu 18.04 system environment. If you use other system versions, you may need to adjust the compilation environment accordingly.

4.3.1 Compile SDK

In the **device/rockchip/rk356x/** directory, there are configuration files of different board types.

Return to SDK root directory to select the configuration file:

```
./build.sh BoardConfig-rk3566-dwin.mk
```

The configuration file will be linked to **device/rockchip/.BoardConfig.mk**, check the file to verify whether the configuration is successful.

4.3.1.1 Partial compilation

- Compile u-boot

```
./build.sh uboot
```

- Compile Kernel

```
./build.sh kernel
```

- Compile recovery

```
./build.sh recovery
```

- Compile Buildroot root filesystem

Compiling the Buildroot root filesystem will generate a compilation output directory in **buildroot/output** :

```
./build.sh rootfs
# Note: Make sure to compile the Buildroot root filesystem as a normal user to avoid unnecessary errors.
```

4.3.1.2 Package the firmware

Update each part of the mirror link to the **rockdev/** directory:

```
./build.sh firmware
```

Pack the firmware, the generated complete firmware will be saved to the **rockdev/pack/** directory.

```
./build.sh updateimg
```

4.4 Upgrade the firmware(40 series & 40ZOS-1 series)

4.4.1 Upgrade the firmware via SD card

To upgrade the firmware using an SD card, you need to use a tool on a computer to write the unified firmware onto the SD card. Currently, this operation is only supported on the Windows operating system.

Operation steps:

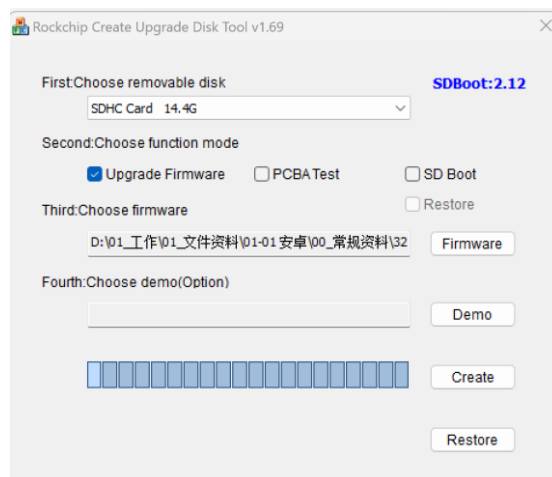
Run SDDiskTool_v1.69, check the “Upgrade Firmware” box and select the correct removable disk device.

Insert SD card into USB card reader and then into USB port of host computer.

Click button “Create” to make it and wait until it is finished.

Remove the SD card, insert it into the SD card slot of the motherboard, power on the board, it will start upgrading automatically.

After the upgrade, remove the SD card and restart the motherboard automatically to complete the whole process of firmware update.



4.4.2 Upgrade the firmware via Micro USB

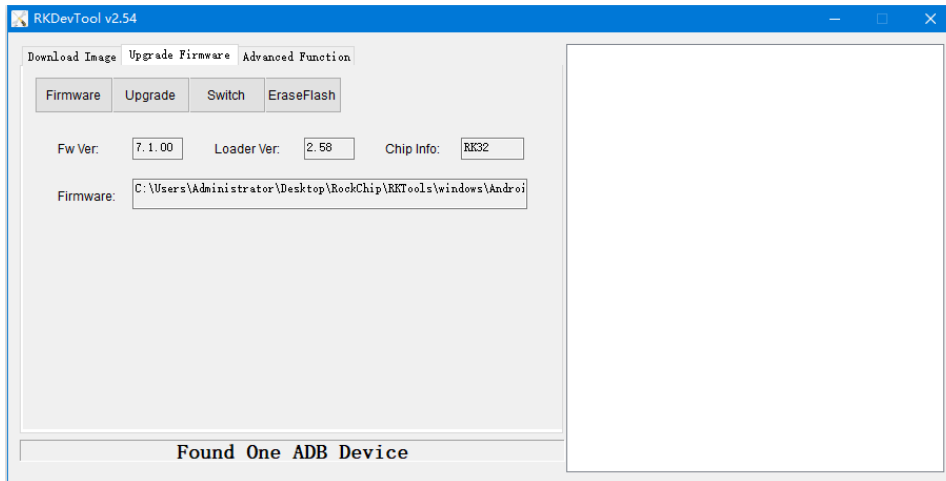
If the computer is being used for the first time to perform the burn-in process, you need to install the driver.

Please refer to the "USB Driver Installation Instructions" in the USB driver directory.

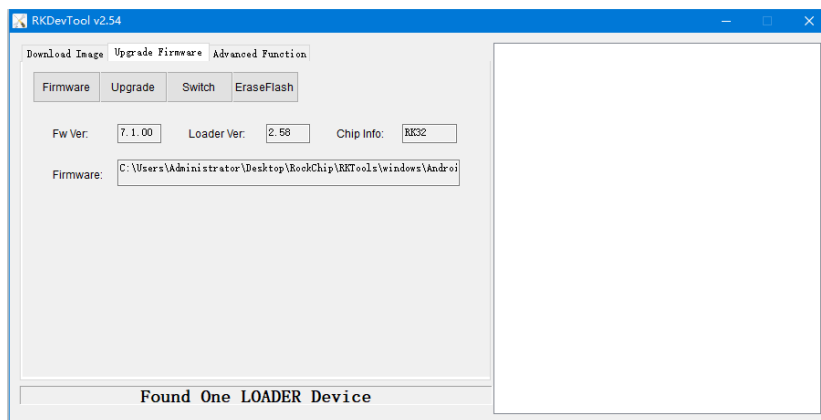
Operation steps:

Download the firmware you need to upgrade to the screen.

Open RKDevTool, select "Upgrade Firmware," and click on "Firmware" to choose the **.img** file to be burned.



While the device is powered off, press and hold the Recover button on the Android screen. First, connect the PC using a USB cable, and then connect the power supply (DC-12V). The following interface will appear. Click "Upgrade" to start the burn-in process. Once the burn-in is complete, the device will automatically restart.



Revision Records

| Rev | Revise Date | Content | Editor |
|-----|-------------|---|------------|
| 00 | 2023-2-20 | First Edition | Yu Yihe |
| 01 | 2023-3-17 | English version | Chen Lvzhi |
| 02 | 2024-3-20 | Added examples about brightness adjustment and system time settings | Chen Yan |
| 03 | 2024-7-25 | Add QT creator compile configurate, compile Linux 4.19 firmware, and chapter 1. | Chen Yan |
| 04 | 2024-11-07 | Add chapter 4.4 (40 series & 40ZOS-1 series) | Chen Xian |

Disclaimer: The product design is subject to alternation and improvement without prior notice.

Please contact us if you have any questions about the use of this document or our products, or if you would like to know the latest information about our products:

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Website: www.dwin-global.com

DWIN Developer Forum: <https://forums.dwin-global.com/index.php/forums>

Thank you all for continuous support of DWIN, and your approval is the driving force of our progress!